

Accurate Symbolic Solution of Ginzburg-Landau Equations in the Circular Cell Approximation by Variational Method: Magnetization of Ideal Type II Superconductor

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How to cite this paper: Chevtchenko, O.A. (2017) Accurate Symbolic Solution of Ginzburg-Landau Equations in the Circular Cell Approximation by Variational Method: Magnetization of Ideal Type II Superconductor. *Journal of Modern Physics*, 8, 982-1011.

<https://doi.org/10.4236/jmp.2017.86062>

Received: April 30, 2017

Accepted: May 28, 2017

Published: May 31, 2017

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Abstract

In this paper I access the degree of approximation of known symbolic approach to solving of Ginzburg-Landau (GL) equations using variational method and a concept of vortex lattice with circular unit cells, refine it in a clear and concise way, identify and eliminate the errors. Also, I will improve its accuracy by providing for the first time precise dependencies of the variational parameters; correct and calculate magnetisation, compare it with the one calculated numerically and conclude they agree within 98.5% or better for any value of the GL parameter k and at magnetic field $0.01 \leq \bar{B}/B_{c2} \leq 1$, which is good basis for many engineering applications. As a result, a theoretical tool is developed using known symbolic solutions of GL equations with accuracy surpassing that of any other known symbolic solution and approaching that of numerical one.

Keywords

Ginzburg-Landau Equations, Accurate Symbolic Solution, Circular Unit Cell

1. Introduction

Much of basic superconductor behavior in magnetic field can be understood from the phenomenological model expressed by two Ginzburg-Landau (GL) equations [1] [2]. Known numerical methods produce excellent and reliable results along with "...difficulty of a numerical solution of the complex-valued GL equations" [3] [4], the demands of calculation effort and time and being less transparent. Calculated magnetisation curves for vortex lattices with rectangular, hexagonal or circular unit cells coincide within line thickness [3]. This fact mo-

tivates solving GL equations symbolically that currently lags behind due to the complexity of the problem [5]-[10]. The lower critical field B_{c1} can be accurately calculated symbolically, see Section 6.1. In strong magnetic fields the symbolic approximation [7] holds, see Section 4.2. At medium magnetic fields a symbolic approximation considering vortex lattice of circular unit cells is developed [5] [6] [8] [10]. The drawbacks of [5] [6] are dealt with in [8] [9] [10] and will not be discussed here. As stated in [8] [9] [10], their method approximately describes magnetic properties of type II superconductors with periodic lattice over the entire range of magnetic fields and for any value of the GL parameter $k = \lambda/\xi \geq k_{12} = 2^{-1/2}$ with λ , ξ London penetration depth and the coherence length respectively. Moreover, the magnetic field dependence of (reversible) magnetisation can be calculated in seconds.

However, a simple check shows that magnetisation calculated with this method ([8] [9] [10], as published) when compared to that calculated numerically [3], has relative differences exceeding 25%, which raises concerns about the accuracy. Clearly, the accuracy of the obtained solution of GL equations is vital: a symbolic one only has added value when its accuracy is comparable to that of the numerics. In this paper I will assess the degree of approximation of the method [8] [9] [10], refine it in a clear, concise and rational way, identify and eliminate the errors. Furthermore, I will improve accuracy of the method by providing for the first time accurate dependencies of the variational parameters; correct and calculate magnetisation, compare it with the one calculated numerically and conclude they agree for any k within 98.5% or better at magnetic field $0.01 \leq \bar{B}/B_{c2} \leq 1$, which is sufficient for many engineering applications.

2. Theoretical Formalism

2.1. Normalisation

In this paper I omit the time-dependent terms in the GL equations written in SI units [11] [12] and use almost the same normalisation as in [3] [11] [12], except that I normalise all length-related quantities by the penetration depth $\lambda = k\xi$ so that both B_{c2} and λ are defined through ξ and **Annex** provides more details. Below there are six mean (averaged over the unit cell area) magnetic field magnitudes (magnetic flux densities) in use: thermodynamic (equilibrium, applied) field B_ϕ , magnetisation M (from the induced currents), the resulting (total) field: $b_m = \bar{b} = \int_0^R b_r \frac{2\pi r dr}{\pi R^2}$ with the local field b_r defined by GL equations in **Table 1**; the lower, the upper and thermodynamic critical magnetic fields: B_{c1} , B_{c2} and $kB_c\sqrt{2} = B_{c2}$ respectively. Furthermore, in this paper $B_{c2} = \frac{\Phi_0}{2\pi\xi^2}$ is considered independent of k or B , defined externally (through ξ and BCS theory [2]) and at the end used as a scaling factor for all magnetic fields; Φ_0 is magnetic flux quantum. Note the local magnetic flux density $b_{zk}(r)/k = B_z(r)/B_{c2} = b_r$ introduced (along with the four other local quantities) in **Table 1** and Section 2.4. Here and below I use the dimensionless units: distance r , modulus of the magnetic vector potential $a_\phi(r)$, modulus of the super-velocity $q_\phi(r)$,

Table 1. Two GL equations written in forms 1, 2 for a unit cell with axial symmetry.

Form 1 [3] [5] [9]	Form 2 [8] [10] [13]
$k^{-2}\Delta f_r - f_r^3 + f_r = f_r(a_r - 1/kr)^2$ (1)	$k^{-2}f_r^3\Delta f_r + f_r^4(1 - f_r^2) = \left(\frac{db_{kr}}{dr}\right)^2$ (3)
$\frac{d}{dr}\left[\frac{d(ra_r)}{rdr}\right] = (a_r - 1/kr)f_r^2$ (2)	$\frac{d}{dr}\left[\frac{d}{rdr}\left(\frac{rb'_{kr}}{f_r^2}\right)\right] = b'_{kr}; \frac{d}{rdr}\left(\frac{r}{f_r^2}\frac{db_{kr}}{dr}\right) = b_{kr}$ (4)

magnetic induction $\bar{b} = b_m = \bar{B}/B_{c2}$ and $\bar{b}_k = \frac{\bar{B}}{\sqrt{2}B_c} = \bar{b}k$, current density $j_\varphi(r)$, magnetic flux quantum $\frac{\Phi_0}{k^2\xi^2\sqrt{2}B_c} = \frac{2\pi}{k}$, the free energy density F and the magnitude $f_r = f(r) = |\psi|$ of the complex GL order parameter ψ are scaled by the dimensioned units: $\lambda = \xi k$, $\xi B_c\sqrt{2}$, $\xi B_c\sqrt{2}$, $B_{c2} = \mu_0 H_{c2}$ and $\sqrt{2}B_c$, $\frac{H_c\sqrt{2}}{\lambda}$, $\lambda^2\mu_0 H_c\sqrt{2}$, $F_c = \mu_0 2H_c^2$ the energy density (μ_0 is magnetic permeability of vacuum) and by the GL coefficients $\sqrt{-\alpha/\beta} = |\psi_0|$ respectively, see **Table A5** for more. All dimensioned units use the International System of Units SI.

2.2. Variational Method

The variational method [5] [6] [8] [9] [10] assumes for the dimensionless modulus $|\psi|$ of the complex-valued order parameter $\psi = f(r)\exp(-ik\vartheta)$ a trial function $f_r = f_r(r)$:

$$|\psi|^2 = f_r^2 = (rf_\infty/\rho_r)^2, \tag{5}$$

where the notation $\rho_r^2 = r^2 + \xi_v^2$ is introduced; the $f_\infty \geq 0$, $\xi_v \neq 0$ are two variational parameters representing respectively the depression of the order parameter due to overlapping vortices and the effective core radius of a vortex; r , φ are the radial coordinate of cylindrical coordinate system and the phase angle respectively (a vortex line is centered on the z-axis, so that $r^2 = x^2 + y^2$; $\varphi = \arctan(y/x)$; x , y , z are rectangular system coordinates, etc. [8]). Both variational parameters f_∞ and ξ_v depend only on magnetic field \bar{b} and on the GL parameter k (**Figures 1-4**), so that e.g., $\rho_r d\rho_r = r dr$. The order parameter ψ is interpreted as the local density of the Cooper pairs and its phase ϑ is determined by the electric potential [12].

2.3. Free Energy Density of Superconductor

Averaged over the cell area Helmholtz dimensionless free energy density F of a circular unit cell (with radius R) has two contributions [3] [8] [9] [10]:

$$F = F_{em} + F_{core}, \tag{6}$$

$$F_{em} = \int_0^R [f_r^2 q_r^2 + b_{kr}^2] \frac{2\pi r dr}{\pi R^2}, \tag{7}$$

$$F_{core} = \int_0^R \left[\frac{1}{2}(1 - f_r^2)^2 + \frac{(f_r')^2}{k^2} \right] \frac{2\pi r dr}{\pi R^2}, \tag{8}$$

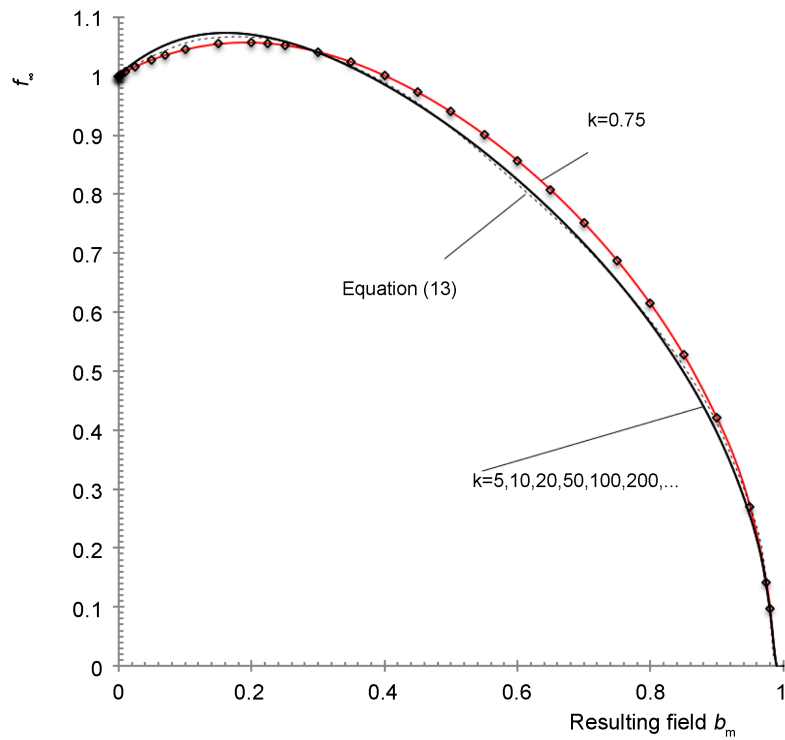


Figure 1. Calculated variational parameter f_∞ vs. magnetic field b_m , all dots from Annex for $k \geq 5$ collapse at one curve approximated by the splines (visible here as the solid black line marked “ $k \geq 5$ ”, the dashed black line is from Equation (18) and the solid red line is the cubic spline fit at $k = 0.75$, indicating the range of the deviation from the curve $k \geq 5$).

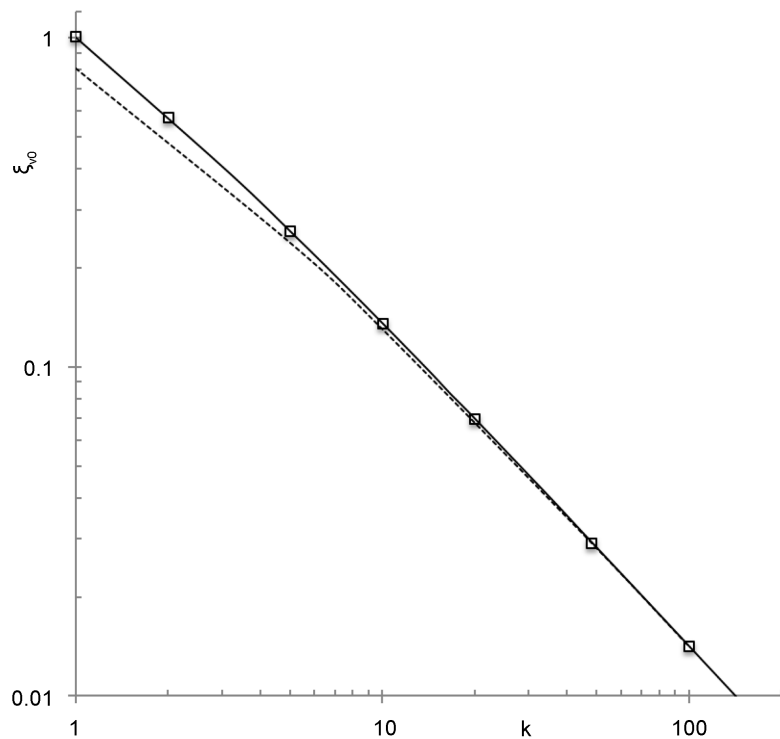


Figure 2. Calculated dependence of the variational parameter $\xi_{v,0}$ on k at $\bar{b} \rightarrow 0$: the boxes represent the data from Annex (the box size corresponds to the relative error of 7%); the solid line—[[5], Equation (16)], the dashed line—[[8], Equation (15)].

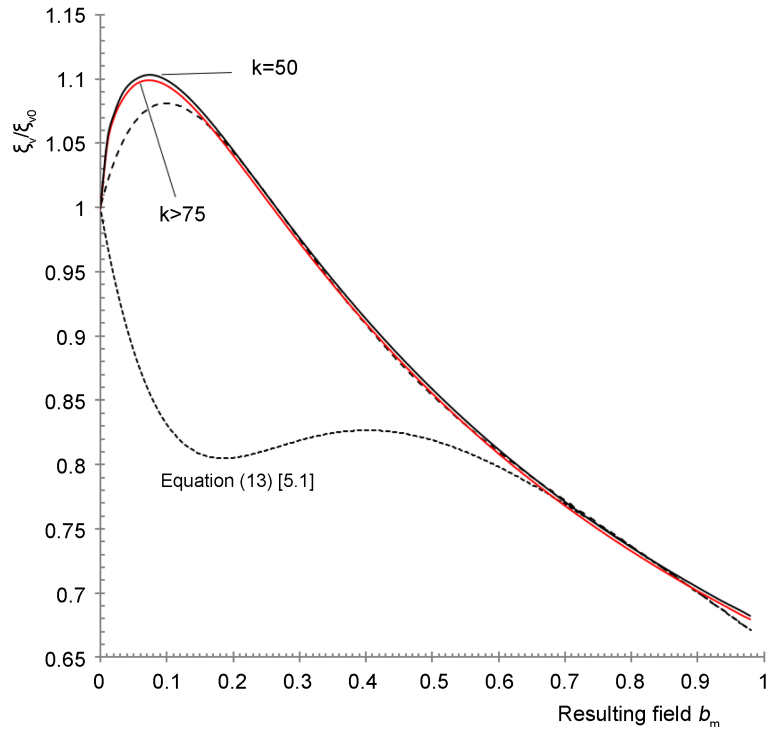


Figure 3. Calculated variational parameter $\xi_v/\xi_{v,0}$ vs. \bar{b} at $k \geq 50$, the solid red line is cubic spline fit to the dots at $k = 100$, see **Annex**; $\xi_{v,0}$ is from Equation (19), the dotted and the dashed lines with no markers are from [[8], Equation (13)] with the constants equal to “-4.3” and “+4.3” respectively.

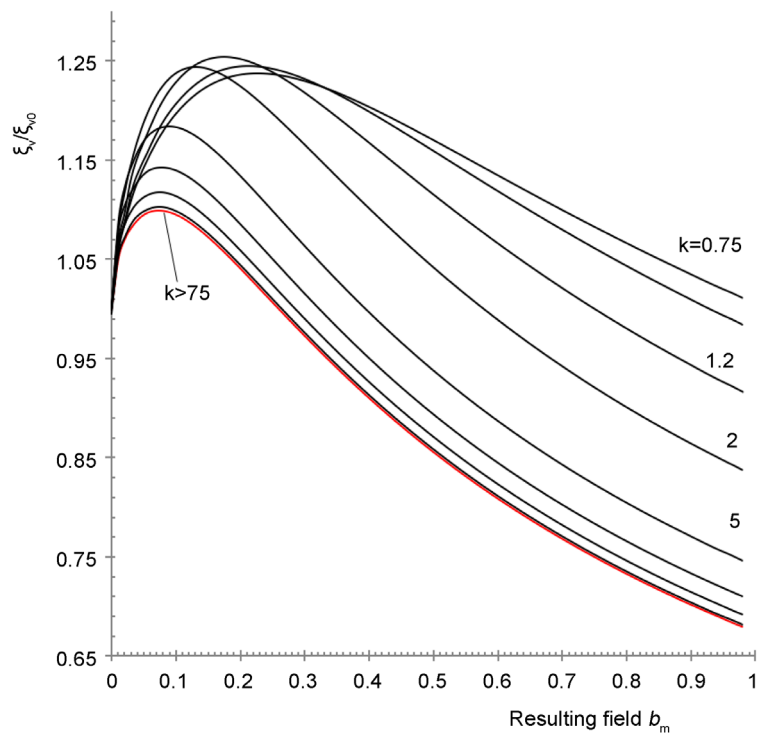


Figure 4. Calculated variational parameter $\xi_v/\xi_{v,0}$ vs. \bar{b} at $k \leq 50$: the solid black lines are cubic spline fits to the dots from **Annex** at $k = 0.75, 0.85, 1.2, 2, 5, 10, 20$ and 50 ; $\xi_{v,0}$ is from Equation (19). The solid red line for $k \geq 75$ is given here as a reference.

where $f'_r = df_r/dr$; F_{em} —is related to super-current and to magnetic field; the first term of F_{core} —to the local density of the Cooper pairs, and the second term: $\frac{(f'_r)^2}{k^2}$ —to their interaction [2] [8] [9] [10] [13]; $\pi R^2 = 2\pi/k\bar{b}_k$ is the area of the circular (Wigner-Seitz) unit cell carrying one magnetic flux quantum, thus $R = \sqrt{2/k\bar{b}_k}$ $f'_r = df_r/dr$ and **Table A5** lists the scaling factors.

2.4. Ginzburg-Landau Equations

The GL equations are obtained by minimising the free energy of superconductor F with respect to e.g., f_r and to q_r (form 1, **Table 1**) or to f_r and b_{kr} (form 2). In the circular cell approximation both the order parameter and magnetic flux density have axial symmetry and for this case two stationary GL equations in two forms are listed in **Table 1**, where the five local quantities: f_r (with

$$\Delta f_r = \frac{d}{rdr} \left(\frac{rd f_r}{dr} \right) = \frac{d^2 f_r}{dr^2} + \frac{df_r}{rdr} = f''_r + f'_r/r, \quad a_r = a_\varphi(r), \quad b_{kr} = b_{kz}(r),$$

$q_r = q_\varphi(r) = a_r - 1/kr$ and $j_r = j_\varphi(r)$ are respectively moduli of the order parameter, of vector potential (satisfying the Coulomb gauge and having only φ -component [5]), of local magnetic flux density vector (having only z -component), of the dimensionless super-velocity (having only φ -component), and of the vortex current density vector (having only φ -component). The two unknowns are: f_r and one of the following: a_r or b_{kr} respectively for the forms 1 or 2.

Complementing the Equations (1) (2) and (3) (4) Maxwell equations are:

$$b_{kr} = \frac{d(rq_r)}{rdr} = \frac{d(ra_r)}{rdr}; \quad j_r = \frac{db_{kr}}{dr} = \frac{d}{dr} \left[\frac{d(rq_r)}{rdr} \right] = q''_r + \frac{q'_r}{r} - \frac{q_r}{r^2}. \quad (9)$$

3. Solving Ginsburg-Landau Equation(s)

From Equations (4) and (5) one gets:

$$\frac{r}{f_r^2} = \frac{\rho_r^2}{f_\infty^2 r} \quad \text{and} \quad \frac{d}{rdr} \left(\frac{\rho_r^2}{r} \frac{db_{kr}}{dr} \right) = f_\infty^2 b_{kr} \quad (10)$$

since f_∞^2 is independent on r . Replacing the variables: $rdr = \rho_r d\rho_r$ in Equation (10) and assuming $\rho_r \neq 0$, $f_\infty \neq 0$ gives:

$$\frac{d}{\rho_r d\rho_r} \left(\frac{\rho_r db_{kr}}{d\rho_r} \right) = \frac{d^2 b_{kr}}{d\rho_r^2} + \frac{db_{kr}}{\rho_r d\rho_r} = f_\infty^2 b_{kr}, \quad \text{or:} \quad \rho_r^2 \frac{d^2 b_{kr}}{d\rho_r^2} + \rho_r \frac{db_{kr}}{d\rho_r} - (f_\infty^2 \rho_r^2 + 0) b_{kr} = 0. \quad (11)$$

Since $\xi_v \neq 0$ (Section 3.4), also $\rho_r \neq 0$ everywhere, see Equation (3). On the other hand, Equation (11) is identical to Equation (4) everywhere except at $f_\infty = 0$, which is the case at $\bar{b} \geq 1$ ($\bar{b}_k \geq k$). Therefore, I conclude that at $\bar{b} \rightarrow 1$ the approach [7] must complement [8] [9] [10] as further elaborated in Section 4.2. At $f_\infty \neq 0$ (and with f_∞ independent on r) Equation (11) is the modified Bessel equation with the solution:

$$b_{kr} = b_{kz}(r) = h_{kz}(r) = c_1 I_0(f_\infty \rho_r) + c_2 K_0(f_\infty \rho_r), \quad (12)$$

where $h_{kz}(r) = H_z(r)/\sqrt{2}H_c$ is magnetic field strength, I_0 and K_0 are the modified Bessel's functions respectively of the first and second kind and order 0;

c_1 and c_2 are the integration constants set by the boundary conditions. So far the solution is the same as obtained in [8] [9] [10]. Moreover, from Equation (12) one obtains:

$$j_r = j_\varphi(r) = b'_{kr} = \frac{f_\infty r db_{kr}}{\rho_r d(f_\infty \rho_r)} = f_\infty r \rho_r^{-1} [c_1 I_1(f_\infty \rho_r) - c_2 K_1(f_\infty \rho_r)] \quad (13)$$

where I_1 and K_1 are the modified Bessel's functions respectively of the first and second kind and order 1. Note that the derivation of the solution (Equations (10)-(13)) was skipped in [8] [9] [10] and as a result, the important restriction $f_\infty \neq 0$ of the solution was hidden so far.

3.1. Boundary Conditions

The boundary conditions can be found e.g., in [3] [5] [6] [8]-[13]. From there a variety follows of the definitions for c_1 and c_2 , such as based upon [8] [9] [10] [13]: 1) quantisation of magnetic flux through the unit cell: $j_r|_{r \rightarrow 0} = -rf_\infty^2/k\xi_v^2$ and 2) zero current at its interface $j_r(R) = 0$:

$$c_1 = \frac{f_\infty K_1(f_\infty \rho_R)}{k\xi_v^2 c_0}, \quad c_2 = \frac{f_\infty I_1(f_\infty \rho_R)}{k\xi_v^2 c_0}, \quad (14)$$

$$c_0 = I_1(f_\infty \rho_R) K_1(f_\infty \xi_v) - I_1(f_\infty \xi_v) K_1(f_\infty \rho_R). \quad (15)$$

In order to stay focused and limit the size of the paper, below I simply accept Equations (14), (15) and will study namely this case in more detail. With the constants c_1 and c_2 defined, the solution allows calculating the local quantities as well as the mean quantities: equilibrium magnetic field, magnetisation, etc. In this paper I focus on magnetisation.

3.2. Variational Method

In the variational method Equation (5) in fact replaces the unknown $f(r)$ (which is otherwise obtained by solving the GL equations) and thus eliminates solving the first GL equation; instead one focuses on solving e.g., for $b_{kz}(r)$ (second GL equation) and for f_∞, ξ_v . While drawbacks of the approach [5] [6] are treated in [8] [9] [10], I find that all three publications [8] [9] [10] are not easy to read as in turn they have crucial errors preventing the reader from wider use of this otherwise excellent method. For instance, in [8] [9] and [10] at least Equations (11), (13), (15); (22), (24), (28) and (2.18), (2.20) respectively have errors that can be decisive for the result. These errors are eliminated here and correct equations are presented thus facilitating broader use of the method. The analytical expressions for the energy density associated with the change in the order parameter near centers of vortices (Equations (15) [6] and (12) [8] respectively) though they look slightly different, are identical. On the other hand, Equation (20) of [9] is a substantial improvement of corresponding Equation (14) of [6] as it is explained in [8] [9] [10] (note that the corresponding Equation (11) [8] contains a typing error, the correct equations are: (2.16) in [10], (20) in [9] and Equation (16) here).

From Equation (12) at $r = 0$, $h_{kr}(0)$ follows and since $F_{em} = \bar{b}_k h_{kr}(0)$, one

gets (from Equations (6)-(8), (14) (15) here) [5] [6] [8] [9] [10]:

$$F_{em} = \bar{b}_k [c_1 I_0(f_\infty \xi_v) + c_2 K_0(f_\infty \xi_v)], \tag{16}$$

$$F_{core} = \frac{(1 - f_\infty^2)^2}{2} + \frac{\bar{b}_1 f_\infty^2}{2} \left[(1 - f_\infty^2) \ln \left(\frac{2}{\bar{b}_1} + 1 \right) + \frac{f_\infty^2}{2 + \bar{b}_1} \right] + \frac{\bar{b}_k f_\infty^2 (1 + \bar{b}_1)}{k (2 + \bar{b}_1)^2}, \tag{17}$$

with $\rho_R = \sqrt{R^2 + \xi_v^2}$ and $\bar{b}_1 = \bar{b}_k k \xi_v^2$.

Minimising the free energy density F of superconductor, Equations (6)-(8), (16) (17), with respect to the variational parameters f_∞ and ξ_v (at fixed k and \bar{b}) allows establishing dependencies of f_∞ and ξ_v on k and \bar{b} in a self-sufficient way [5] [6] [8] [9] [10], see detailed in **Figures 1-4** and **Annex**. Once these are established, the order parameter is defined (Equation (5)) and the dependence of magnetisation on k and \bar{b} follows, see Equations (20)-(23) (24). In [5] [6] [8] [9] [10], the accurate dependencies of f_∞ and ξ_v on k and \bar{b} are missing, instead inaccurate interpolation fits are published in both cases as explained below and clear from **Figures 1-4**. This prevents accurate calculation of magnetisation in particular. In this paper the minimising of F is done numerically (using Solver in Excel), results are presented in a clear, traceable form and in more detail as compared to [5] [6] [8] [9] [10] and they yield the following.

3.3. Variational Parameter f_∞

At any $5 \leq k \leq 200$ all obtained data points of the dependence $f_\infty(\bar{b}, k)$ collapse at one curve fitted here by a cubic spline, see **Figure 1** and **Table A1**. For this reason no data for the individual splines is given here for this range. This simplification causes an estimated error of 0.5% as explained in Section 5 and the error can be reduced by using more accurate data from the minimising of F . Furthermore, the obtained data are in reasonable agreement with that from [8], Equation (14)] (numbered as Equation (18) here), except at lower ($\bar{b} < 0.25$) and at higher ($\bar{b} > 0.75$) fields, see **Figure 1**:

$$f_\infty(\bar{b}) = \left(1 - \frac{\bar{b}^2}{2.8} \right) \left\{ \left[1 + 1.7\bar{b} (1 - 1.4\bar{b})^2 \right] \left[1 - \left(\frac{\bar{b}}{0.985} \right)^4 \right] \right\}^{1/2}. \tag{18}$$

At $k_{12} \leq k < 5$ the obtained dots deviate from this curve and the error when using Equation (18) can reach 5% as **Figure 1** exemplifies. Therefore in this range instead of using **Figure 1** or Equation (18), I recommend using **Figure 1** or more accurately the data from **Annex** e.g., by constructing the individual splines. Importance of this correction becomes clear in Section 5. For the above reasons I am convinced that Equation (18) does not approximate the dependence of $f_\infty(\bar{b}, k)$ with “an accuracy of about 0.5% for arbitrary k and \bar{b} ” as stated in [8] [9] [10]. In addition, I find unsatisfactory the agreement of the obtained data with the Equation (24) of [6]:

$$f_\infty(\bar{b}) = 1 - (\bar{b})^4.$$

3.4. Variational Parameter ξ_v

Minimisation of F with respect to ξ_v at $\bar{b} \rightarrow 0$ shows that Equation (15) of

[8] is less accurate than the original Equation (16) of [5], especially at $k < 10$ (and that the error exceeds 1% up to $k = 50$), see **Figure 2**. Therefore, the correct equation to calculate the dependence $\xi_{v,0}(k)$ for $\bar{b} \rightarrow 0$ at any k in an ideal type II superconductor is [5]:

$$k\xi_{v,0} = \sqrt{2} \left[1 - \frac{K_0^2(\xi_{v,0})}{K_1^2(\xi_{v,0})} \right]^{\frac{1}{2}}. \tag{19}$$

The obtained (by minimizing F) dependence $\xi_v(\bar{b}, k)$ is similar and different from those described in [3] [5]. On one hand at $k \geq 75$ all data points collapse practically at one curve, see **Figure 3** and **Table A2** in **Annex**. For this reason only one cubic spline fit (namely, $k = 100$) is shown, the error of this simplification is below 0.5%.

The agreement of the obtained data with [[8], Equation (13)] is unsatisfactory, see **Figure 3** and therefore I recommend calculating $\xi_v(\bar{b}, k)$ for $k \geq 75$ and any value of magnetic field \bar{b} from the spline fit, **Figure 3** and **Table A2** in **Annex**.

On the other hand at $k < 50$ the obtained dependence $\xi_v(\bar{b}, k)$ is rather different from those described in [5] [6] [8] [9] [10] and from the single curve $k \geq 75$ in **Figure 3**. For instance, the relative difference for $k = 50$ and 0.75 reaches 50% as **Figure 4** shows.

Based on this study, I conclude that none of the Equations (13)-(15) in [8] (repeated as (22)-(24) in [9] and as (2.18)-(2.20) in [10]) is accurate for arbitrary values of $k \geq k_{12}$ and over the entire range of magnetic fields $0 \leq \bar{b} \leq 1$. Instead I recommend using more accurate data from this paper, see **Annex**. The most accurate results are obtained through minimising the free energy density F of superconductor with respect to the variational parameters f_∞ and ξ_v as described in this paper. This step is a must when aiming at the agreement better than 1% between magnetisation calculated symbolically and numerically, see Section 5.

4. Magnetisation (Derived Symbolically)

4.1. Variational Approach

The applied (thermodynamic, equilibrium) magnetic field $b_{ka}(\bar{b}_k) = \frac{\partial F}{2\partial \bar{b}_k}$

from Equations (14)-(17) according to [5] [6] [8] [9] [10] is:

$$b_{ka}(\bar{b}_k) = b_{ka}^{em}(\bar{b}_k) + b_{ka}^{core}(\bar{b}_k), \tag{20}$$

with [8]:

$$b_{ka}^{em}(\bar{b}_k) = b_{ka}^{em1}(\bar{b}_k) + b_{ka}^{em2}(\bar{b}_k), \tag{21}$$

$$b_{ka}^{em1}(\bar{b}_k) = \frac{1}{2} [c_1 I_0(f_\infty \xi_v) + c_2 K_0(f_\infty \xi_v)], \tag{22}$$

$$b_{ka}^{em2}(\bar{b}_k) = \frac{c_0^{-2}}{2k\bar{b}_k \rho_R^2}, \tag{23}$$

$$b_{ka}^{core}(\bar{b}_k) = \frac{k f_\infty^2 \xi_v^2}{2} \left[\frac{1-f_\infty^2}{2} \ln \left(1 + \frac{2}{\bar{b}_1} \right) - \frac{1-f_\infty^2}{2+\bar{b}_1} + \frac{f_\infty^2}{(2+\bar{b}_1)^2} \right] + \frac{f_\infty^2 (2+3\bar{b}_1)}{2k^2 (2+\bar{b}_1)^3} \quad (24)$$

and $\bar{b}_1 = \bar{b}_k k \xi_v^2$. Since Equations (21)-(24) define the applied field $b_{ka}(\bar{b}_k)$, the magnetisation is:

$$-m_{k0}(\bar{b}_k) = b_{ka}(\bar{b}_k) - \bar{b}_k \quad \text{or:} \quad -m_{k0}(b_{ka}) = b_{ka} - \bar{b}_k(b_{ka}), \quad m_{k0}(\bar{b}) = \frac{M_0(\bar{B})}{B_c \sqrt{2}}. \quad (25)$$

Finally, after re-normalisation of Equation (25), one obtains:

$$-m_0(\bar{b}) = b_a(\bar{b}) - \bar{b} \quad \text{with} \quad m_0(\bar{b}) = M_0(\bar{B})/B_{c2}. \quad (26)$$

Namely the magnetization $-m_0(\bar{b})$ calculated from Equation (25) after correcting the error (see Section 4.2) becomes the magnetization $-m_1(\bar{b})$ compared in Section 5 to those calculated numerically and with other symbolic methods.

4.2. The Error and the Correction

The error (present in Equations (10)-(26) at $f_\infty \rightarrow 0$, see. Equations (10)-(11)) is evident from the Abrikosov solution of the linearized GL equations [7] stating:

$$m_4 = m_4(b_a, k) = \frac{b_a - 1}{(2k^2 - 1)\beta_A} \quad (27)$$

for any k and $\bar{b} \rightarrow 1$ with β_A equal to 1.1803 (1.1596) for the vortex lattice with square (hexagonal) unit cells [4] and to 1.1576 for the lattice with circular cells [9]; $b_a = \frac{B_a}{B_{c2}}$, $m_4 = \frac{M_4}{B_{c2}}$. As the examples in Section 5 will illustrate, at $\bar{b} \rightarrow 1$ the line 5 ([8] [9] [10] representing the magnetisation calculated from Equations (25) (26) without corrections) crosses the line 4 representing the m_4 and moreover it crosses the horizontal axis at 0.985 (instead of at 1 as Equation (27) implies). The error in $m_0(\bar{b})$ is visible at least at $0.5 \leq b_a \leq 1$.

In this paper the error is eliminated in the following way. The Equations (21)-(26) are only valid at $f_\infty \neq 0$, see Equation (11). Otherwise, Equation (27) is the correct symbolic solution of GL equation(s) providing the missing additional conditions to Equations (21)-(26) and simply stating that in the plane $-m_1(b_a)$ the point m_{c2} on the true magnetisation curve m_1 has the following coordinates: $m_{c2}(1, 0)$, in other words: $m_1|_{b_a=1} = 0$ and at $\bar{b} \rightarrow 1$

$$\frac{dm_4}{db_a} = \frac{m_4}{1-b_a} = \frac{-1}{(2k^2 - 1)\beta_A}, \quad (28)$$

the 1st derivative through this point of the true magnetisation curve should be constant set by Equation (28) and that only depends on k and on the Abrikosov parameter $\beta_A > 1$ [7]. Moreover, using Equation (30) and F_{\min} (that follows from the minimising the free energy in Equations (16) (17)), we can now define more accurately the vague condition “ $\bar{b} \rightarrow 1$ ” (or “ $1 - b_a \ll 1$ ” [3]) as:

$$\bar{b}_3 \leq \bar{b} \leq 1 \quad \text{with} \quad \bar{b}_3 \quad \text{being defined by the condition:} \quad F_{\min} = F_4. \quad (29)$$

From [[7], Equation (19)] it is clear that at $\bar{b}_3 \leq \bar{b} \leq 1$ the free energy density (see Equations (6)-(8)) is (at minimum when β_A is as close to 1 as possible):

$$F_4 = \left[\frac{1}{2} + \bar{b}_k^2 - \frac{(1 - \bar{b}_k)^2}{1 + (2k^2 - 1)\beta_A} \right]. \quad (30)$$

From Equations (30) and (16) (17) it is easy to check that for $\beta_A = 1.1576$, $k = 200$ at $0.5 \leq \bar{b} \leq 1$ always $F_{\min} > F_4$, which means that in this range Equation (27) is more accurate than Equation (26). On the other hand, at $0 \leq \bar{b} \leq 0.5$ Equation (26) is more accurate than Equation (27), since here $F_4 > F_{\min}$ (with F_{\min} obtained by minimising F , see Equations (16) (17)). More generally, Equation (27) must be used at $\bar{b}_3 \leq \bar{b} \leq 1$ instead of Equation (26).

A smooth transition from Equation (26) to Equation (27) can be achieved in several ways. In this paper I use the following approach. So far calculated from Equation (26) magnetisation $m_0|_{b_a=0.985} = 0$. Thus Equation (26) produces the erroneous value of the upper critical field b_{c2}^* (see Section 6.2) due to ignoring the restriction $f_\infty \neq 0$, see the condition by Equations (10) and (11). Replacing \bar{b} by $\bar{b}/0.985$ (Equation (33)) when plotting $m(\bar{b})$ satisfies the condition set by Equation (27) at $\bar{b} \rightarrow 1$: $m_0|_{b_a=1} = 0$. This step shifts the entire magnetisation curve (Equation (26)) parallel to itself and slightly to the right as exemplified in Section 5. Moreover, at $\bar{b} \rightarrow 1$ calculated from Equation (26) magnetisation should have the same first derivative as set by Equation (28). This is obviously not the case as one can see in Section 5 (not only magnetisation curve calculated from [8] [9] [10] crosses the horizontal axis at $b_m = 0.985$, but it has the slope different from that set by Equation (27)).

In this paper a compliance with this condition (Equation (28)) is achieved by introducing the correction: $m_1 = 0.985 \cdot m_0(\bar{b})$, where $m_0(\bar{b})$ comes from Equation (26). This correction slightly rotates the entire magnetisation curve around the point $m_{c2}(1,0)$, so that the derivative of the magnetisation m_1 becomes equal to that set by Equation (28) and the transition from m_1 to m_4 is smooth since the higher derivatives are preserved. Furthermore, used for the comparison (in Section 5) magnetisation m_2 from [[3], Figure 7] is calculated numerically for the triangular vortex lattice, while the obtained here results are for the vortex lattice of circular cells, therefore accounting the respective ratio of the Abrikosov parameters (Equation (27)), more accurately: $m_1 = 0.983 \cdot m_0(\bar{b})$ in this case. Clearly, more sophisticated methods of achieving the same result can be used (all required math for combining the solutions is present e.g., in [13]), but they are beyond the scope of this paper.

In conclusion, the correction makes the obtained solution compliant with [7] [13] (the same point m_{c2} and the same direction of the magnetisation curve at this point). It should be noted that this correction of the magnetisation uses the symbolic form of the theoretical result [7] at $\bar{b} \rightarrow 1$ and therefore the solution obtained here remains self-sufficient (even though it now uses two solutions of GL equations: [8] [9] [10] and [7]). So far I did not use any numerical results (the fact that calculated numerically magnetisation m_2 also agree with the conditions of Equations (27), (28) only means that these conditions are just). Cor-

rected this way magnetisation m_1 is in excellent agreement with the conditions of Equations (27), (28) and is further compared to that calculated numerically (and with other symbolic methods) in **Figures 5-8**.

5. Comparison and Discussion

In **Figures 5-8** the magnetisation m_1 is compared to that calculated numerically [3] and to those calculated symbolically [7] [8] [9] [10] through the entire range of magnetic fields $0 \leq \bar{b} \leq 1$ and representative range of the GL parameter $k_{12} \leq k \leq 200$ (same range as in [3]). In each figure the magnetisation changes between 0 and $-m_{c1} = b_{c1}$ (further defined in Section 6.1). Moreover, in this range of k the b_{c1} changes by more than 4 orders in magnitude: between 1 and 7.2×10^{-5} . An overview can be found elsewhere [3] [4] of the general features of reversible magnetisation, of its dependence on k and on magnetic field, etc. as follows from numerical solving of GL equations and these are not discussed here. Instead, I focus on the validation of the obtained analytical solution (Equations (20)-(26) complemented by Equations (27)-(30) and with the data in **Figures 1-4** and **Annex**). This is achieved by comparing magnetization m_1 to magnetisation calculated using other methods. Namely, in **Figures 5-8** I compare m_1 to $m_2 - m_5$ being respectively magnetisation calculated from: this work (m_1); [3] [4], numerically for hexagonal unit cells (m_2); [3], Equation (19)] from the interpolation fit for m_2 with limited validity (m_3); [7], Equation (27) here (m_4) and [8] [9] [10] as published (m_5).

As clear from **Figures 5-8**, for any value of the GL parameter $k \geq k_{12}$ and over the entire range of magnetic fields $0 \leq b_m = \bar{b} \leq 1$ excellent agreement between m_1 and m_2 is achieved: the relative difference $\left| \frac{m_1 - m_2}{m_2} \right|$ is below 1.5% everywhere (except in the narrow range: $0 \leq b_m \leq 0.01$ where it is below 4%, see further elaborated in Section 6.1).

5.1. Ginzburg-Landau Parameter $k_{12} \leq k \leq 1$

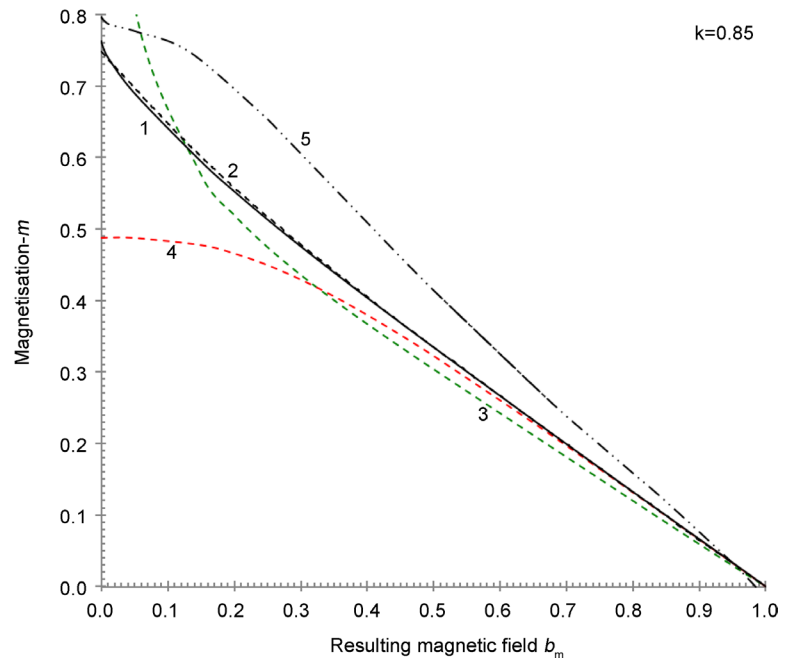
Representative for the range of $k_{12} \leq k \leq 1$ (with $0.58 \leq m_{c1} = b_{c1} \leq 1$, see [[3], **Figure 1**]) set of the magnetisation curves at $k = 0.85$ is shown in **Figure 5(a)**.

The relative difference $\left| \frac{m_1 - m_2}{m_2} \right|$ is below 1.5% in the entire range

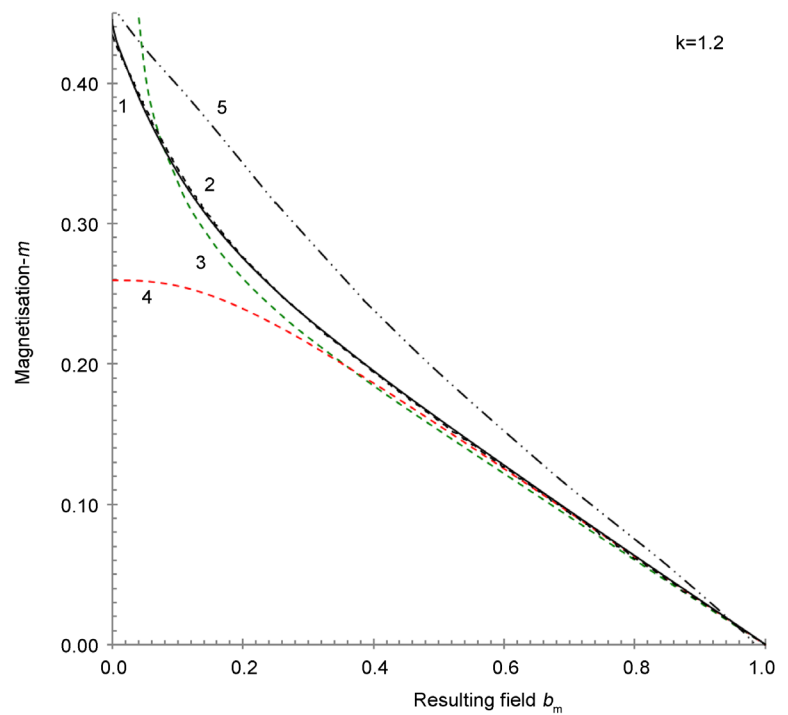
$0 \leq b_m = \bar{b} \leq 1$ (except in the range: $0 \leq b_m \leq 0.01$ where it is below 4%, see further elaborated in Section 6.1). As expected [3], the interpolation fit (m_3) totally fails to describe the data (m_2) quantitatively, since $k < 3$ and thus

$\left| \frac{m_3 - m_2}{m_2} \right|$ is too high. The data represented by magnetisation m_1 (and m_2) are in good agreement with these represented by m_4 at $0.8 \leq \bar{b} \leq 1$ (so that both

and $\left| \frac{m_2 - m_4}{m_4} \right|$ e.g., at $\bar{b} = 0.8$ are below 0.7%, even though $\bar{b}_3 = 1$ as $k < 1$ in

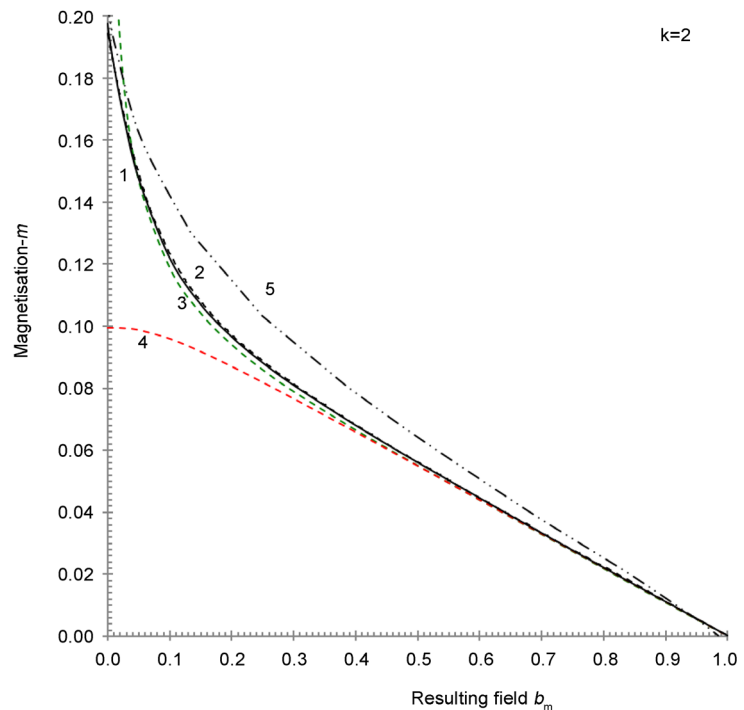


(a)

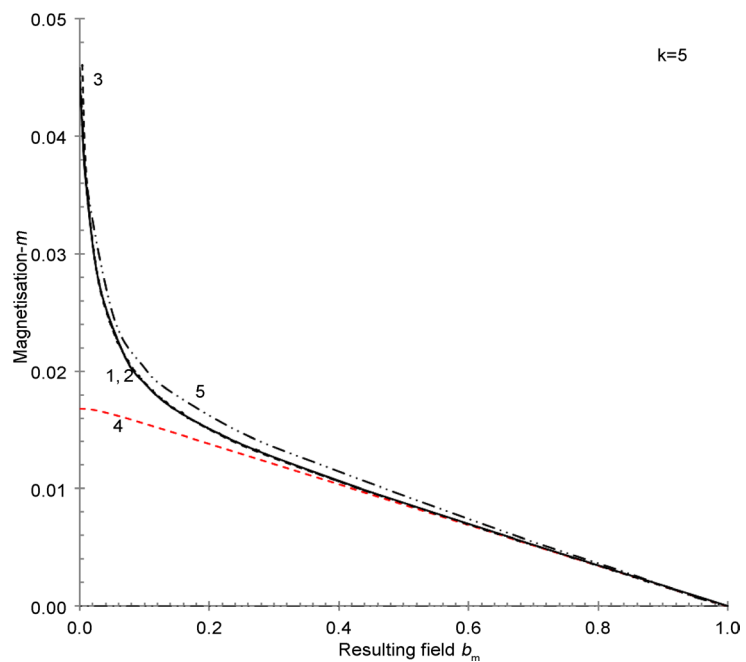


(b)

Figure 5. (a). Calculated for $k = 0.85$ magnetisation m as function of the resulting field $\bar{b} = b_m$: 1—as proposed here (m_1); 2, 3—from the numerical solution, the dashed black line (m_2) restored from [[3], **Figure 7**] and the dashed green line (m_3) from the fit—[[3], Equation (19)]; 4—from Equation (27) (m_4); 5—from [8] [9] [10] (dashed double dotted line, m_5). (b). Calculated for $k = 1.2$ magnetisation m as function of the resulting field $\bar{b} = b_m$: 1—as proposed here (m_1); 2, 3—from the numerical solution, the dashed black line (m_2) restored from [[3], **Figure 7**] and the dashed green line (m_3) from the fit—[[3], Equation (27)]; 4—from Equation (27) (m_4); 5—from [8] [9] [10] (dashed double dotted line, m_5). The line numbering is the same as in **Figure 5(a)**.

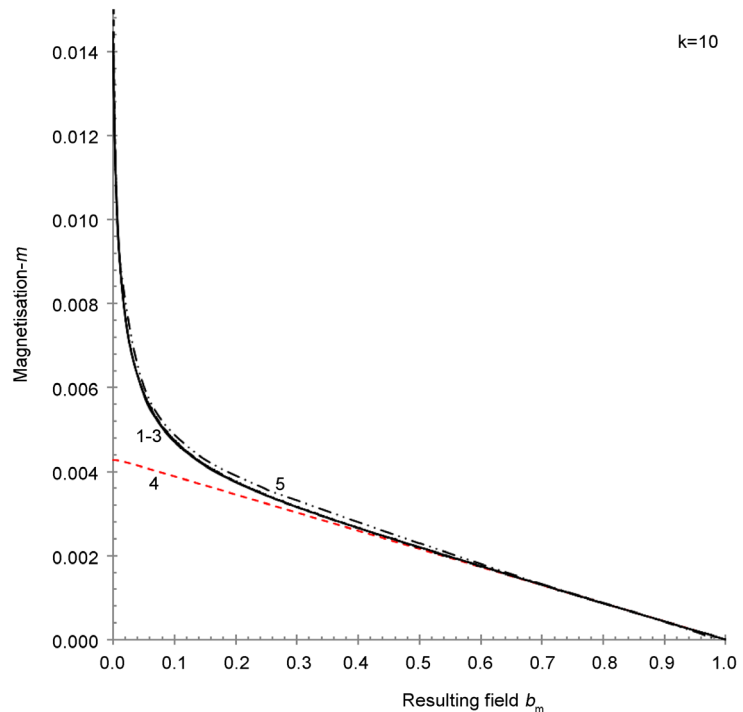


(a)

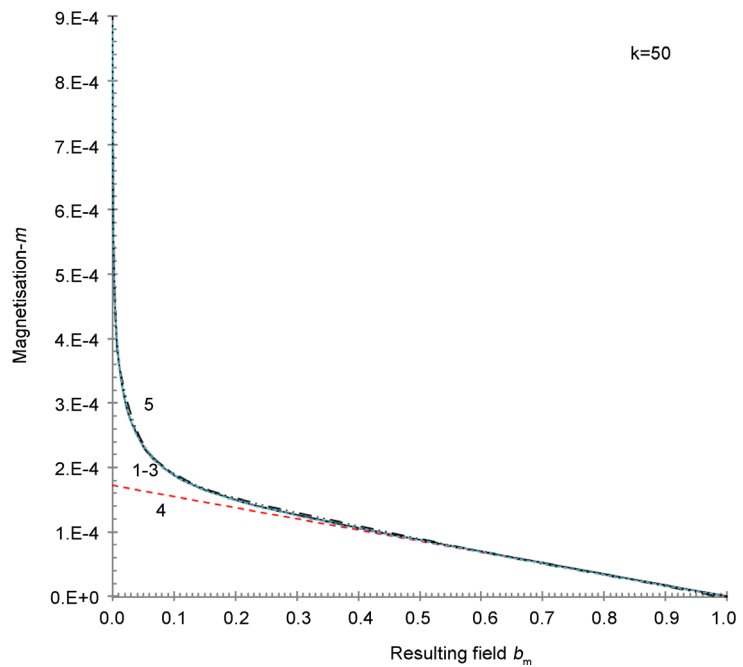


(b)

Figure 6. (a) Calculated for $k = 2$ magnetisation m as function of the field $\bar{b} = b_m$: 1—as proposed here (m_1); 2, 3—from the numerical solution, the dashed black line (m_2) restored from [[3], Figure 7] and the dashed green line (m_3) from the fit—[[3], Equation (19)]; 4—from Equation (27) (m_4); 5—from [8] [9] [10] (dashed double dotted line, m_5). The line numbering is the same as in Figure 5(a). (b). Calculated for $k = 5$ magnetisation m as function of the field $\bar{b} = b_m$: 1—as proposed here (m_1); 2, 3—from the numerical solution, the dashed black line (m_2) restored from [[3], Figure 7] and the dashed green line (m_3) from the fit—[[3], Equation (19)]; 4—from Equation (27) (m_4); 5—from [8] [9] [10] (dashed double dotted line, m_5). The line numbering is the same as in Figure 5(a).

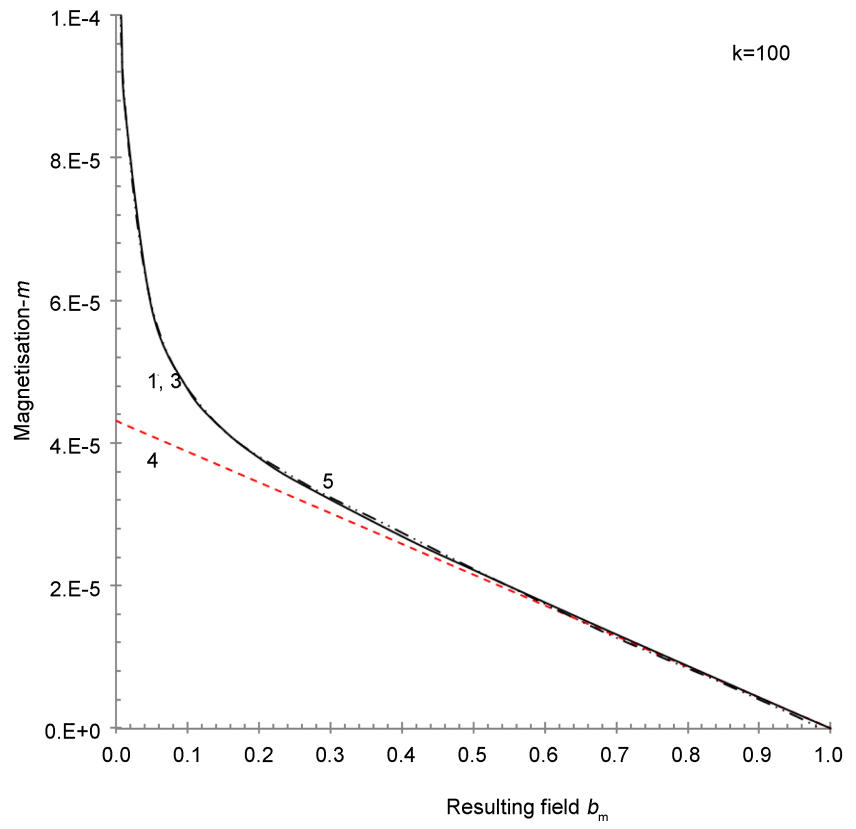


(a)

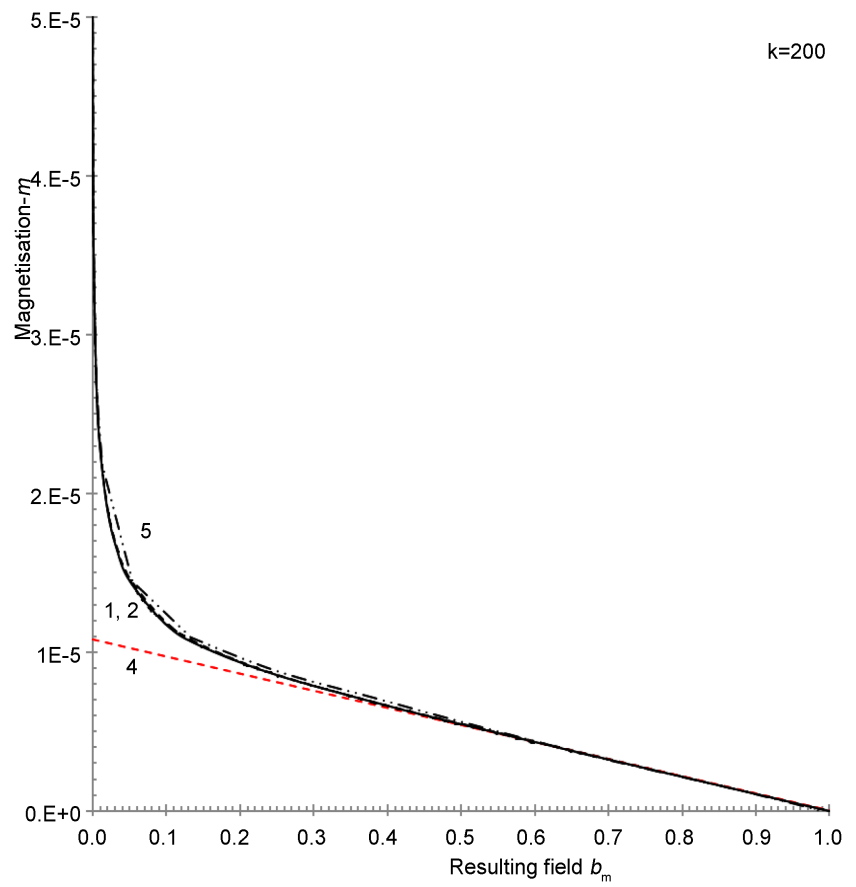


(b)

Figure 7. (a) Calculated for $k = 10$ magnetisation m as function of the field $\bar{b} = b_m$: 1—as proposed here (m_1); 2, 3—from the numerical solution, the dashed black line (m_2) restored from [[3], Figure 7] and the dashed green line (m_3) from the fit—[[3], Equation (19)]; 4—from Equation (27) (m_4); 5—from [8] [9] [10] (dashed double dotted line, m_5). The line numbering is the same as in Figure 5(a). (b) Calculated for $k = 50$ magnetisation m as function of the field $\bar{b} = b_m$: 1—as proposed here (m_1); 2, 3—from the numerical solution, the dashed black line (m_2) restored from [[3], Figure 7] and the dashed green line (m_3) from the fit—[[3], Equation (19)]; 4—from Equation (27) (m_4); 5—from [8] [9] [10] (dashed double dotted line, m_5). The line numbering is the same as in Figure 5(a).



(a)



(b)

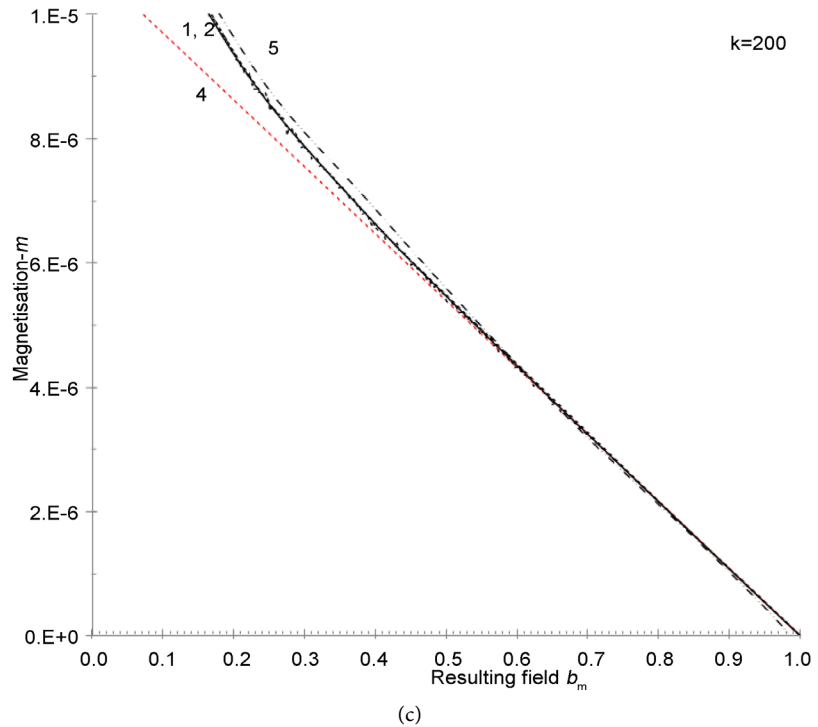


Figure 8. (a) Calculated for $k = 100$ magnetisation m as function of the field $\bar{b} = b_m$: 1—as proposed here (m_1); 2, 3—from the numerical solution, the dashed black line (m_2) restored from [[3], **Figure 7**] and the dashed green line (m_3) from the fit—[[3], Equation (19)]; 4—from Equation (27) (m_4); 5—from [8] [9] [10] (dashed double dotted line, m_5). The line numbering is the same as in **Figure 5(a)**. (b) Calculated for $k = 200$ magnetisation m as function of the field $\bar{b} = b_m$: 1—as proposed here (m_1); 2, 3—from the numerical solution, the dashed black line (m_2) restored from [[3], **Figure 7**] and the dashed green line (m_3) from the fit—[[3], Equation (19)]; 4—from Equation (27) (m_4); 5—from [8] [9] [10] (dashed double dotted line, m_5). The line numbering is the same as in **Figure 5(a)**. (c) Fragment of the calculated for $k = 200$ magnetisation m as function of the field $\bar{b} = b_m$, see **Figure 8(b)** for more. The line numbering is the same as in **Figure 5(a)**.

this case). It is clear from the figure that m_5 also fails to describe quantitatively the data represented by m_1 (and m_2): e.g., at $b_m = 0.25$ the relative difference $\left| \frac{m_5 - m_2}{m_2} \right|$ is 26.5%, which is not competitive and not what one expects after reading [8] [9] [10].

5.2. Ginzburg-Landau Parameter $1 \leq k \leq 2$

Representative for the range of $1 \leq k \leq 2$ (with $0.2 \leq m_{c1} = b_{c1} \leq 0.58$, see [[3], **Figure 1**]) set of the magnetisation curves $k = 1.2$ and $k = 2$ is shown in **Figure 5(b)** and **Figure 6(a)** respectively.

In **Figure 5(b)** and **Figure 6(a)** the relative differences $\left| \frac{m_1 - m_2}{m_2} \right|$ are below 1.1% and 1.3% respectively in the entire range $0 \leq b_m = \bar{b} \leq 1$ (except in the range: $0 \leq b_m \leq 0.01$ where they are below 4% and 3.2% respectively, as further elaborated in Section 6.1). As expected [3], the interpolation fit (m_3) fails to de-

scribe the data (m_2) quantitatively, since $k < 3$ and thus $\left| \frac{m_3 - m_2}{m_2} \right|$ is high. The data represented by m_1 (and m_2) are in good agreement with these represented by m_4 at $0.8 \leq \bar{b} \leq 1$ (so that both $\left| \frac{m_1 - m_4}{m_4} \right|$ and $\left| \frac{m_2 - m_4}{m_4} \right|$ e.g., at $\bar{b} = 0.8$ are below 0.4% (**Figure 5(b)**) and below 0.2% (**Figure 6(a)**), with $\bar{b}_3 = 0.94$ and 0.75 respectively). It is clear from the figures that m_5 fails to describe quantitatively the data represented by m_1 (and m_2): e.g., at $b = 0.25$ the relative difference $\left| \frac{m_5 - m_2}{m_2} \right|$ is 24.5% (**Figure 5(b)**) and 16.1% (**Figure 6(a)**), which is not competitive and not what one expects after reading [8] [9] [10].

5.3. Ginzburg-Landau Parameter $2 \leq k \leq 5$

Representative for the range of $2 \leq k \leq 5$ (with $0.045 \leq m_{c1} = b_{c1} \leq 0.2$, see [[3], **Figure 1**]) set of the magnetisation curves $k = 2$ and $k = 5$ is shown in **Figure 6(a)** and **Figure 6(b)** respectively. In **Figure 6(b)** the relative difference $\left| \frac{m_1 - m_2}{m_2} \right|$ is below 0.5% in the entire range of magnetic fields $0 \leq b_m = \bar{b} \leq 1$ (except in the range: $0 \leq b_m \leq 0.01$ where it is below 2% respectively, as further elaborated in section 6.1). As expected [3] the interpolation fit (m_3) describes the data (m_2) quantitatively, since $k > 3$ and thus $\left| \frac{m_3 - m_2}{m_2} \right|$ is small, so both are represented by almost the same line in the figure. The data represented by m_1 (and m_2) are in good agreement with these represented by m_4 at $0.7 \leq \bar{b} \leq 1$ (so that both $\left| \frac{m_1 - m_4}{m_4} \right|$ and $\left| \frac{m_2 - m_4}{m_4} \right|$ e.g., at $\bar{b} = 0.7$ are below 0.3%, with $\bar{b}_3 = 0.6$). It is clear from **Figure 6(b)** that m_5 still fails to describe quantitatively the data represented by m_1 (and m_2): e.g., at $b_m = 0.25$ the relative difference $\left| \frac{m_5 - m_2}{m_2} \right|$ is 7%, which is not competitive and not what one expects after reading [8] [9] [10].

5.4. Ginzburg-Landau Parameter $5 \leq k \leq 10$

Representative for the range of $5 \leq k \leq 10$ (with $0.014 \leq m_{c1} = b_{c1} \leq 0.045$, see [[3], **Figure 1**]) set of the magnetisation curves at $k = 5$ and $k = 10$ is shown in **Figure 6(b)** and **Figure 7(a)** respectively. In **Figure 7(a)** the relative difference $\left| \frac{m_1 - m_2}{m_2} \right|$ is below 1% in the entire range $0 \leq b_m = \bar{b} \leq 1$ (except in the range: $0 \leq b_m \leq 0.01$ where it is below 1.3% respectively, as further elaborated in section 6.1). As expected the interpolation fit (m_3) describes the data (m_2) quantitatively, since $k > 3$ and thus $\left| \frac{m_3 - m_2}{m_2} \right|$ is small [3] so both are represented by

almost the same line in the figure. The data represented by m_1 (and m_2) are in good agreement with these represented by m_4 at $0.7 \leq \bar{b} \leq 1$ (so that both $\left| \frac{m_1 - m_4}{m_4} \right|$ and $\left| \frac{m_2 - m_4}{m_4} \right|$ e.g., at $\bar{b} = 0.7$ are below 0.4%, with $\bar{b}_3 = 0.54$). It is clear from **Figure 7(a)** that m_5 describes quantitatively the data represented by m_1 (and m_2): with larger relative difference $\left| \frac{m_5 - m_2}{m_2} \right|$ of e.g., 4% at $b = 0.25$ (as compared to $\left| \frac{m_1 - m_2}{m_2} \right|$) and with visible error in the magnetisation's first derivative (on \bar{b}).

5.5. Ginzburg-Landau Parameter $10 \leq k \leq 50$

Representative for the range of $10 \leq k \leq 50$ (with $8.8 \times 10^{-4} \leq m_{c1} = b_{c1} \leq 0.014$) set of the magnetisation curves at $k = 10$ and $k = 50$ is shown in **Figure 7(a)** and **Figure 7(b)** respectively. In **Figure 7(b)** the relative difference $\left| \frac{m_1 - m_2}{m_2} \right|$ is below 0.6% in the entire range $0 \leq b_m = \bar{b} \leq 1$. As expected the interpolation fit (m_3) describes the data (m_2) quantitatively, since $k > 3$ and thus $\left| \frac{m_3 - m_2}{m_2} \right|$ is small [3] so both are represented by almost the same line in the figure. The data represented by m_1 (and m_2) are in good agreement with these represented by m_4 at $0.7 \leq \bar{b} \leq 1$ (so that both $\left| \frac{m_1 - m_4}{m_4} \right|$ and $\left| \frac{m_2 - m_4}{m_4} \right|$ e.g., at $\bar{b} = 0.7$ are below 0.5%, with $\bar{b}_3 = 0.51$). It is clear from **Figure 7(a)** that m_5 describes quantitatively the data represented by m_1 (and m_2): with larger relative difference $\left| \frac{m_5 - m_2}{m_2} \right|$ of e.g., 3% at $b = 0.25$ (as compared to $\left| \frac{m_1 - m_2}{m_2} \right|$) and the error in the magnetisation first derivative (on \bar{b}) is present.

5.6. Ginzburg-Landau Parameter $50 \leq k \leq 200$

Representative for the range of $50 \leq k \leq 200$ (with $7.2 \times 10^{-5} \leq m_{c1} = b_{c1} \leq 8.8 \times 10^{-4}$) set of the magnetisation curves at $k = 100$ and $k = 200$ is shown in **Figure 8(a)** and **Figure 8(b)** respectively. Since the accurate numerical data for $k = 100$ are absent [3], we use m_3 instead of m_2 in **Figure 8(a)**. The relative difference $\left| \frac{m_1 - m_3}{m_3} \right|$ is below 1% (**Figure 8(a)**) and $\left| \frac{m_1 - m_2}{m_2} \right|$ below 0.6% (**Figure 8(b)**) in the entire range $0 \leq b_m = \bar{b} \leq 1$. The data in **Figure 8(a)** represented by m_1 (and m_3) are in good agreement with these represented by m_4 at $0.7 \leq \bar{b} \leq 1$ (so that both $\left| \frac{m_1 - m_4}{m_4} \right|$ and $\left| \frac{m_3 - m_4}{m_4} \right|$ e.g., at $\bar{b} = 0.75$ are below 1%, with $\bar{b}_3 = 0.52$). The data in **Figure 8(b)** represented

by m_1 (and m_2) are in good agreement with these represented by m_4 at $0.7 \leq \bar{b} \leq 1$ (so that both $\left| \frac{m_1 - m_4}{m_4} \right|$ and $\left| \frac{m_2 - m_4}{m_4} \right|$ e.g., at $\bar{b} = 0.7$ are below 0.3%, with $\bar{b}_3 = 0.5$). It is clear from **Figure 8(a)** that m_5 describes quantitatively the data represented by m_1 (and m_3) with larger relative difference $\left| \frac{m_5 - m_2}{m_2} \right|$ of e.g., 2% at $b = 0.25$ (as compared to $\left| \frac{m_1 - m_3}{m_3} \right|$) and the error in the magnetisation 1st derivative (on \bar{b}) is present. It is clear from **Figure 8(b)** that m_5 describes quantitatively the data represented by m_1 (and m_2) with larger relative difference $\left| \frac{m_5 - m_2}{m_2} \right|$ of e.g., 4% at $b = 0.25$ (as compared to $\left| \frac{m_1 - m_2}{m_2} \right|$) and the error in the magnetisation's first derivative (on \bar{b}) is present.

5.7. Ginzburg-Landau Parameter $k = 200$

The fragment of the magnetisation curve at $k = 200$ exemplifies that the error in the 1st derivative of the magnetization m_5 is present at highest values of k and results in the noticeable difference $\left| \frac{m_5 - m_1}{m_1} \right|$. The noise of the magnetisation m_2 caused by the digitalisation of the data [[3], **Figure 7**] is also visible in the figure.

To summarise, over the entire ranges of the GL parameter $k_{12} \leq k \leq 1000$ and of magnetic field $0 \leq b_m = \bar{b} \leq 1$ excellent agreement between m_1 and m_2 is achieved: the relative difference $\left| \frac{m_1 - m_2}{m_2} \right|$ is below 1.5% everywhere (except at the narrow range: $0 \leq b_m \leq 0.01$ where it is below 4% as elaborated in section 6.1). This result validates the advanced symbolic approach of this paper. On the other hand, for the first time numerical results [3] for hexagonal and circular unit cells are accurately validated over the entire ranges of k and b_m in a transparent way with the (essentially independent) symbolic method of solving GL equations. Moreover, I find that the obtained close agreement of m_1 and m_2 makes some of the interpolation fits [[3], Equations (15)-(23)] obsolete. Clearly, the remaining discrepancy of m_1 and m_2 can be reduced by expanding the data sets in **Annex** (the simplification error is now about 0.5%), making the direct comparison of the underlying data, revising the symbolic solution and the boundary conditions, etc. This however is beyond the scope of this paper. It must be noted, that magnetisation calculated from Equations (20)-(26) is rather sensitive to the errors in calculating the variational parameters. Therefore, in order to avoid the interpolation errors in calculating f_∞ and ξ_v (that can be caused e.g., by splines), values of f_∞ , ξ_v and m are best calculated at exactly the same values of \bar{b} and k .

Presented in **Annex** data for the dependencies of f_∞ and ξ_v on k and \bar{b} contain the simplification error of up to 0.5% (caused by the limit in the size of the paper). I recommend that when aiming at the agreement better than 99%

between magnetisation calculated symbolically and numerically, one has to use more accurate data obtained through the minimising the free energy density F of superconductor with respect to the variational parameters f_∞ and ξ_v . Thus obviously “In order to achieve self-consistency in the theory the dependencies $\xi_v(k, \bar{b})$ and $f_\infty(k, \bar{b})$ should be obtained by numerically minimising the function $F(k, \bar{b}, \xi_v, f_\infty)$ with respect to ξ_v and f_∞ ” [8] [9] [10], to which I add: the minimisation procedure is straightforward, use Equations (6) (7) (8), (16) (17) and a standard optimisation program, such as commonly available Solver in Excel. I find the quote above missing the “how” part (almost as to write: in order to get solution of GL equations, solve them).

6. The Critical Fields

6.1. The Lower Critical Field b_{c1}

In this paper I calculate values of the field b_{c1} from Equations (25) (26) typically at $\bar{b} < 1 \times 10^{-6}$, since at $\bar{b} = 0$ the Equation (25) diverges. In **Figure 9** the boxes show calculated this way dependence $b_{c11}(k)$ of the lower critical field b_{c1} . The black solid line is calculated from the fit to the numerical results [3] [4]:

$$b_{c12} = \left\{ \ln(k) + \alpha_\infty + \exp[-c_0 - c_1 \ln(k) - c_2 \ln^2(k)] \right\} \quad (20)$$

with $\alpha_\infty = 0.49693$; $c_0 = 0.41477$; $c_1 = 0.775$; $c_2 = 0.1303$.

The red dashed line is calculated from the symbolic expression for isolated flux line [5] [6]:

$$b_{c13} = \left(\xi_{v0}^2 + k^{-2} \right) / 8 + K_0(\xi_{v0}) / \left[2k^2 \xi_{v0} K_1(\xi_{v0}) \right]. \quad (32)$$

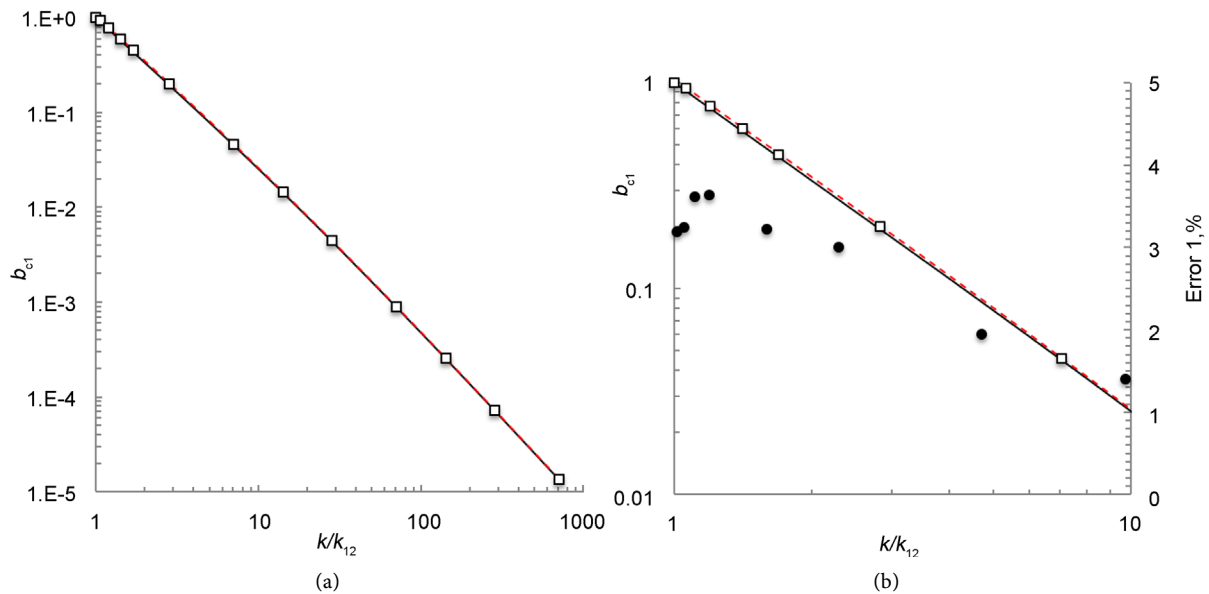


Figure 9. Calculated dependence on k of the lower critical field b_{c1} , (a): boxes—this paper (b_{c10}); the solid black line—numerically, Equation (31) (b_{c12}); the dashed line—Equation (32) (b_{c13}); (b): fragment of the same, the black circles—the relative “error”, %: $\frac{b_{c11} - b_{c12}}{b_{c12}}$.

In this range of k the b_{c1} changes by 5 orders of magnitude, so I find the agreement between b_{c11} , b_{c12} and b_{c13} reasonable (at $k < 0$ there is still room for improvement).

6.2. The Upper Critical Field b_{c2}

As noted [8] [9] [10], and clear from **Figures 5-8** and **Annex**, the value of the upper critical field b_{c2}^* following from the symbolic approach [8] [9] [10] is 1.5% lower than the true value of $b_{c2} = 1$ and therefore the correction is introduced in order to have the same upper critical point:

$$b_{c2}^{corr} = b_{c2}^*/0.985 = 1 = b_{c2}. \quad (33)$$

This correction is dealt with in section 4.2. Moreover, **Figure 10** shows the values of F_{\min} , (derived from Equations (16) (17) through the minimisation procedure) corresponding to the data in **Annex**. The box on each curve corresponds to the value of magnetic field b_3 (Equation (29)), and separates the areas of validity for Equations (25) (26) and (27) valid respectively to the left or to the right from the box for any $k > 1$. Presented values of F_{\min} can be used as a reference when comparing different methods of solving GL equations.

Finally, in order to illustrate the common feature of the ideal superconducting

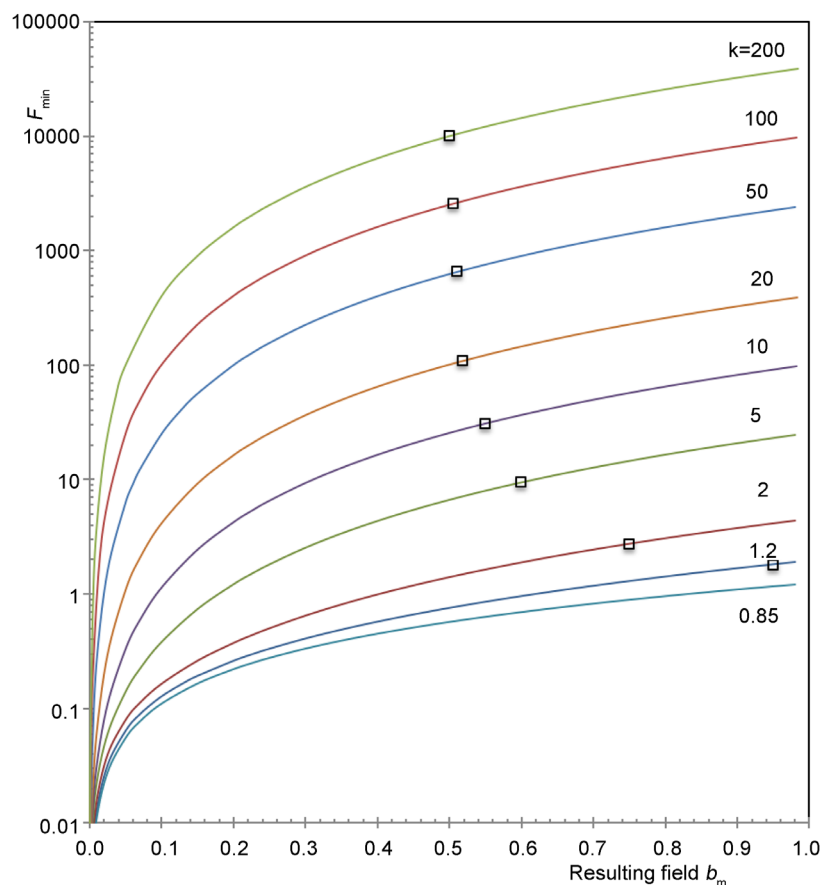


Figure 10. Minimum value F_{\min} of the free energy density F (Equation (16) (17)) as function of the resulting magnetic field b_m for the selected values of k (shown next to the corresponding lines).

materials (in this case homogeneous, bulk, elliptically shaped, edge- and pin-free, placed in uniform magnetic field), in **Figure 11** I show the magnetisation calculated for selected values of $k = 34; 50$ and 75 (typical for Nb_3Sn ; NbTi and REBCO respectively) and assuming vortex lattice with hexagonal unit cells. The solid lines represent m_1 as proposed here; the dashed line – m_3 (interpolated from the fit [[3], Equation (19)]). The scaling factor m_{40} for the magnetisation in all cases is derived from Equation (28) (assuming $b_a = 0$), in addition to that the scaling factor of 6 is used in order to keep the magnetisation values below 1 in the figure. Scaled this way magnetic field dependence of the magnetisation for these very different materials in the field range $0.001 \leq \bar{b} \leq 1$ collapse practically at the same curve. At lower magnetic fields there is a stratification depending on the k value, besides m_3 gives errors as expected [3] that are higher at lower k .

7. Conclusion

Known symbolic method [5] [6] [8] [9] [10] of solving Ginzburg-Landau equations has limited validity. Namely, assumed dependencies (interpolation fits) for the variational parameters f_∞ and ξ_v on the Ginzburg-Landau parameter k

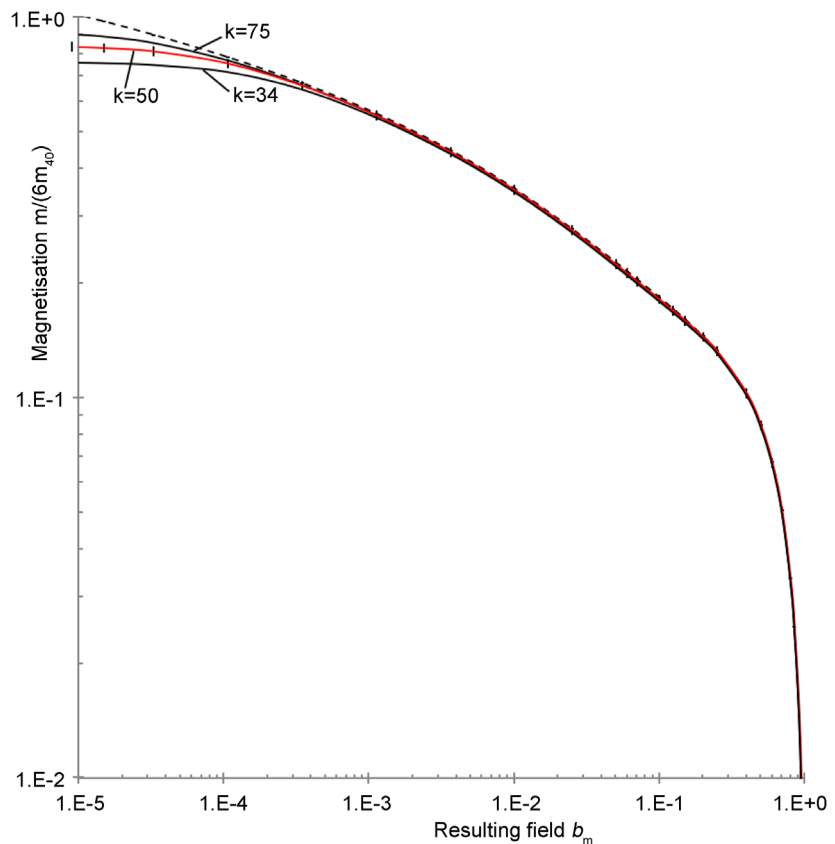


Figure 11. Calculated for $k = 34, 50$ and 75 magnetisation as function of the field $\bar{b} = b_m$: the solid lines— m_1 as proposed here; the dashed line— m_3 (interpolated from the fit [[3], Equation (19)]). The scaling factor for the magnetisation in all cases is derived from Equation (28), in addition to that the scaling factor of 6 is used in order to keep the magnetisation ranging from 0.01 to 1 in the figure. The $\pm 3\%$ relative error (the vertical bars) is guide for an eye.

and on magnetic flux density \bar{b} are inaccurate and result in unacceptably high errors (reaching 25% and more). This limits applicability of otherwise excellent method. In the paper I eliminate several errors, extract and combine accurate symbolic solutions from the above and from [7] and provide for the first time precise dependencies for f_∞ and ξ_v on k and \bar{b} together with the simple and validated way of minimising the free energy density of superconductor. Resulting good agreement (98.5% for the entire range of magnetic flux density: $0.01 \leq \bar{b} \leq 1$ and any value of the parameter $k > 1/\sqrt{2}$) between the advanced symbolic and the known numerical solutions of Ginzburg-Landau equations validates both and hopefully will result in wider use of the symbolic approach.

Acknowledgements

If you are interested to support this study, contact the author at: o.a.chevtchenko@gmail.com. If you are interested in the results, contact us at: <http://www.hts-powercables.nl>. This research is funded privately and all rights belong to the author. Many thanks to A. A. Shevchenko for helping with difficult parts of this study, to R. Bakker for the inspirational atmosphere, to prof.-em. J. J. Smit for his support of this approach. A word of disgrace goes personally to Mr Jose Labastida, head of scientific department and to prof.-em. Helga Nowotny, former president of ERC, who chose to deny a funding for this study and thus created obstacles on the way to this result that could otherwise be published years earlier.

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Annex

Accurate dependencies of the variational parameters $\xi_v(k, \bar{b})$ and $f_\infty(k, \bar{b})$ obtained from the minimising the free energy density F, see Equations (16) (17) (Tables A1-A4). The dimensional and dimensionless quantities and scaling factors (Table A5).

Note that in order to simplify comparisons with [8] [9] [10] in Tables A1-A4 the values of \bar{b} are not corrected (by 0.985).

Table A1. Spline data for the calculated variational parameter f_∞ at $0.75 \leq k \leq 200$.

$k = 0.75$		$k = 0.85$		$k = 1.2$		$k = 2$		$5 \leq k \leq 200$	
\bar{b}	f_∞	\bar{b}	f_∞	\bar{b}	f_∞	\bar{b}	f_∞	\bar{b}	f_∞
7.26E-6	1.000E+0	5.95E-6	1.000E+0	2.96E-6	1.000E+0	1.05E-6	1.000E+0	5.80E-10	1.000E+0
3.46E-4	1.001E+0	3.46E-4	1.001E+0	3.46E-4	1.001E+0	3.46E-4	1.001E+0	3.456E-4	1.001E+0
1.12E-3	1.001E+0	1.12E-3	1.001E+0	1.12E-3	1.002E+0	1.12E-3	1.002E+0	1.121E-3	1.002E+0
4.00E-3	1.004E+0	3.68E-3	1.004E+0	3.68E-3	1.004E+0	2.00E-3	1.003E+0	3.682E-3	1.005E+0
1.00E-2	1.008E+0	1.00E-2	1.009E+0	1.00E-2	1.010E+0	3.68E-3	1.005E+0	1.287E-2	1.014E+0
2.50E-2	1.017E+0	2.50E-2	1.018E+0	2.50E-2	1.020E+0	7.00E-3	1.008E+0	2.500E-2	1.024E+0
5.00E-2	1.029E+0	5.00E-2	1.030E+0	5.00E-2	1.034E+0	1.00E-2	1.011E+0	5.000E-2	1.042E+0
7.00E-2	1.036E+0	7.00E-2	1.038E+0	7.00E-2	1.043E+0	2.00E-2	1.019E+0	7.000E-2	1.053E+0
1.00E-1	1.046E+0	1.00E-1	1.048E+0	1.00E-1	1.054E+0	3.50E-2	1.029E+0	1.000E-1	1.065E+0
1.50E-1	1.056E+0	1.50E-1	1.058E+0	1.50E-1	1.064E+0	5.00E-2	1.038E+0	1.500E-1	1.073E+0
2.00E-1	1.058E+0	2.00E-1	1.060E+0	2.00E-1	1.065E+0	7.00E-2	1.048E+0	2.000E-1	1.071E+0
2.25E-1	1.056E+0	2.25E-1	1.058E+0	2.25E-1	1.062E+0	1.00E-1	1.060E+0	2.250E-1	1.066E+0
2.50E-1	1.053E+0	2.50E-1	1.055E+0	2.50E-1	1.057E+0	1.50E-1	1.070E+0	2.500E-1	1.059E+0
3.00E-1	1.042E+0	3.00E-1	1.042E+0	3.00E-1	1.042E+0	2.00E-1	1.068E+0	3.000E-1	1.040E+0
3.50E-1	1.025E+0	3.50E-1	1.024E+0	3.50E-1	1.021E+0	2.25E-1	1.064E+0	3.500E-1	1.016E+0
4.00E-1	1.002E+0	4.00E-1	9.996E-1	4.00E-1	9.939E-1	2.50E-1	1.058E+0	4.000E-1	9.860E-1
4.50E-1	9.738E-1	4.50E-1	9.701E-1	4.50E-1	9.621E-1	3.00E-1	1.041E+0	4.500E-1	9.519E-1
5.00E-1	9.404E-1	5.00E-1	9.355E-1	5.00E-1	9.255E-1	3.50E-1	1.018E+0	5.000E-1	9.136E-1
5.50E-1	9.018E-1	5.50E-1	8.959E-1	5.50E-1	8.843E-1	4.00E-1	9.891E-1	5.500E-1	8.712E-1
6.00E-1	8.579E-1	6.00E-1	8.511E-1	6.00E-1	8.384E-1	4.50E-1	9.558E-1	6.000E-1	8.245E-1
6.50E-1	8.082E-1	6.50E-1	8.009E-1	6.50E-1	7.873E-1	5.00E-1	9.181E-1	6.500E-1	7.730E-1
7.00E-1	7.521E-1	7.00E-1	7.444E-1	7.00E-1	7.305E-1	5.50E-1	8.761E-1	7.000E-1	7.162E-1
7.50E-1	6.884E-1	7.50E-1	6.806E-1	7.50E-1	6.668E-1	6.00E-1	8.296E-1	7.500E-1	6.529E-1
8.00E-1	6.152E-1	8.00E-1	6.075E-1	8.00E-1	5.943E-1	6.50E-1	7.782E-1	8.000E-1	5.812E-1
8.50E-1	5.288E-1	8.50E-1	5.217E-1	8.50E-1	5.095E-1	7.00E-1	7.214E-1	8.500E-1	4.978E-1
9.00E-1	4.217E-1	9.00E-1	4.156E-1	9.00E-1	4.054E-1	7.50E-1	6.579E-1	9.000E-1	3.957E-1
9.50E-1	2.708E-1	9.50E-1	2.667E-1	9.50E-1	2.598E-1	8.00E-1	5.858E-1	9.500E-1	2.534E-1
9.75E-1	1.421E-1	9.75E-1	1.398E-1	9.75E-1	1.362E-1	8.50E-1	5.020E-1	9.750E-1	1.327E-1
9.80E-1	9.740E-2	9.80E-1	9.586E-2	9.80E-1	9.333E-2	9.00E-1	3.991E-1	9.800E-1	9.099E-2
9.85E-1	1.000E-4	9.85E-1	1.000E-4	9.85E-1	1.000E-4	9.50E-1	2.556E-1	9.825E-1	5.995E-2
						9.60E-1	2.154E-1	9.830E-1	5.162E-2
						9.70E-1	1.656E-1	9.850E-1	1.000E-4
						9.80E-1	9.180E-2		
						9.85E-1	1.000E-4		

Table A2. Spline data for the calculated variational parameter ξ_v/ξ_{v0} at $k \geq 50$.

$k=50$		$k=100$		$k=200$	
\bar{b}	ξ_v/ξ_{v0}	\bar{b}	ξ_v/ξ_{v0}	\bar{b}	ξ_v/ξ_{v0}
7.025E-9	9.989E-1	9.090E-6	1.000E+0	1.318E-10	1.000E+0
9.000E-6	1.001E+0	3.287E-5	1.002E+0	1.000E-6	1.000E+0
1.500E-5	1.001E+0	1.073E-4	1.003E+0	9.090E-6	1.001E+0
3.287E-5	1.002E+0	3.456E-4	1.007E+0	3.287E-5	1.001E+0
1.073E-4	1.004E+0	1.121E-3	1.014E+0	1.073E-4	1.003E+0
3.456E-4	1.008E+0	3.682E-3	1.029E+0	3.456E-4	1.006E+0
1.121E-3	1.016E+0	1.287E-2	1.056E+0	1.121E-3	1.014E+0
3.682E-3	1.031E+0	2.500E-2	1.075E+0	5.000E-3	1.033E+0
1.000E-2	1.052E+0	5.000E-2	1.095E+0	2.000E-2	1.067E+0
2.500E-2	1.079E+0	7.000E-2	1.099E+0	5.000E-2	1.093E+0
5.000E-2	1.098E+0	1.000E-1	1.095E+0	1.000E-1	1.094E+0
7.000E-2	1.103E+0	1.500E-1	1.072E+0	1.500E-1	1.071E+0
1.000E-1	1.099E+0	2.000E-1	1.041E+0	2.000E-1	1.040E+0
1.500E-1	1.076E+0	2.250E-1	1.024E+0	2.250E-1	1.023E+0
2.000E-1	1.044E+0	2.500E-1	1.006E+0	2.500E-1	1.006E+0
2.250E-1	1.027E+0	3.000E-1	9.725E-1	3.000E-1	9.718E-1
2.500E-1	1.010E+0	3.500E-1	9.402E-1	3.500E-1	9.395E-1
3.000E-1	9.759E-1	4.000E-1	9.098E-1	4.000E-1	9.092E-1
3.500E-1	9.435E-1	4.500E-1	8.816E-1	4.500E-1	8.810E-1
4.000E-1	9.130E-1	5.000E-1	8.553E-1	5.000E-1	8.548E-1
4.500E-1	8.847E-1	5.500E-1	8.310E-1	5.500E-1	8.305E-1
5.000E-1	8.583E-1	6.000E-1	8.084E-1	6.000E-1	8.079E-1
5.500E-1	8.339E-1	6.500E-1	7.875E-1	6.500E-1	7.869E-1
6.000E-1	8.113E-1	7.000E-1	7.679E-1	7.000E-1	7.674E-1
6.500E-1	7.902E-1	7.500E-1	7.497E-1	7.500E-1	7.492E-1
7.000E-1	7.706E-1	8.000E-1	7.326E-1	8.000E-1	7.321E-1
7.500E-1	7.523E-1	8.500E-1	7.166E-1	8.500E-1	7.161E-1
8.000E-1	7.352E-1	9.000E-1	7.015E-1	9.000E-1	7.010E-1
8.500E-1	7.191E-1	9.500E-1	6.874E-1	9.400E-1	6.893E-1
9.000E-1	7.040E-1	9.750E-1	6.805E-1	9.500E-1	6.869E-1
9.500E-1	6.898E-1	9.800E-1	6.792E-1	9.600E-1	6.837E-1
9.750E-1	6.829E-1	9.825E-1	6.785E-1	9.700E-1	6.815E-1
9.800E-1	6.817E-1	9.830E-1	6.784E-1	9.790E-1	6.786E-1
9.850E-1	6.817E-1	9.850E-1	6.784E-1	9.840E-1	6.774E-1

Table A3. Spline data for the calculated variational parameter ξ_v/ξ_{v0} at $0.75 < k \leq 2$.

$k = 0.75$		$k = 0.85$		$k = 1.2$		$k = 2$	
\bar{b}	ξ_v/ξ_{v0}	\bar{b}	ξ_v/ξ_{v0}	\bar{b}	ξ_v/ξ_{v0}	\bar{b}	ξ_v/ξ_{v0}
7.258E-6	1.001E+0	5.954E-6	9.946E-1	2.962E-6	1.000E+0	3.287E-5	1.001E+0
9.000E-6	1.001E+0	7.000E-6	9.946E-1	9.000E-6	1.000E+0	1.073E-4	1.001E+0
1.500E-5	1.001E+0	9.000E-6	9.946E-1	1.000E-5	1.000E+0	3.456E-4	1.008E+0
3.287E-5	1.001E+0	3.287E-5	9.946E-1	3.287E-5	1.000E+0	1.121E-3	1.019E+0
1.073E-4	1.001E+0	1.073E-4	9.946E-1	1.073E-4	1.000E+0	2.000E-3	1.027E+0
3.456E-4	1.006E+0	3.456E-4	1.006E+0	3.456E-4	1.007E+0	3.682E-3	1.041E+0
1.121E-3	1.013E+0	1.121E-3	1.014E+0	1.121E-3	1.016E+0	7.000E-3	1.061E+0
4.000E-3	1.031E+0	3.682E-3	1.031E+0	3.682E-3	1.035E+0	1.000E-2	1.076E+0
1.000E-2	1.056E+0	1.000E-2	1.059E+0	1.000E-2	1.066E+0	2.000E-2	1.116E+0
2.500E-2	1.097E+0	2.500E-2	1.102E+0	2.500E-2	1.115E+0	3.500E-2	1.157E+0
5.000E-2	1.142E+0	5.000E-2	1.149E+0	5.000E-2	1.168E+0	5.000E-2	1.188E+0
7.000E-2	1.168E+0	7.000E-2	1.177E+0	7.000E-2	1.198E+0	7.000E-2	1.215E+0
1.000E-1	1.197E+0	1.000E-1	1.206E+0	1.000E-1	1.229E+0	1.000E-1	1.237E+0
1.500E-1	1.225E+0	1.500E-1	1.234E+0	1.337E-1	1.247E+0	1.500E-1	1.242E+0
2.000E-1	1.236E+0	2.000E-1	1.244E+0	1.500E-1	1.252E+0	2.000E-1	1.224E+0
2.250E-1	1.237E+0	2.250E-1	1.244E+0	2.000E-1	1.252E+0	2.250E-1	1.211E+0
2.500E-1	1.236E+0	2.500E-1	1.242E+0	2.250E-1	1.247E+0	2.500E-1	1.196E+0
3.000E-1	1.230E+0	3.000E-1	1.231E+0	2.500E-1	1.239E+0	3.000E-1	1.165E+0
3.500E-1	1.218E+0	3.500E-1	1.216E+0	3.000E-1	1.218E+0	3.500E-1	1.133E+0
4.000E-1	1.203E+0	4.000E-1	1.198E+0	3.500E-1	1.194E+0	4.000E-1	1.101E+0
4.500E-1	1.187E+0	4.500E-1	1.179E+0	4.000E-1	1.168E+0	4.500E-1	1.070E+0
5.000E-1	1.170E+0	5.000E-1	1.159E+0	4.500E-1	1.141E+0	5.000E-1	1.041E+0
5.500E-1	1.152E+0	5.500E-1	1.138E+0	5.000E-1	1.115E+0	5.500E-1	1.014E+0
6.000E-1	1.134E+0	6.000E-1	1.118E+0	5.500E-1	1.090E+0	6.000E-1	9.885E-1
6.500E-1	1.117E+0	6.500E-1	1.098E+0	6.000E-1	1.066E+0	6.500E-1	9.643E-1
7.000E-1	1.099E+0	7.000E-1	1.079E+0	6.500E-1	1.043E+0	7.000E-1	9.417E-1
7.500E-1	1.082E+0	7.500E-1	1.061E+0	7.000E-1	1.021E+0	7.500E-1	9.204E-1
8.000E-1	1.066E+0	8.000E-1	1.043E+0	7.500E-1	1.000E+0	8.000E-1	9.004E-1
8.500E-1	1.050E+0	8.500E-1	1.025E+0	8.000E-1	9.803E-1	8.500E-1	8.815E-1
9.000E-1	1.035E+0	9.000E-1	1.009E+0	8.500E-1	9.614E-1	9.000E-1	8.637E-1
9.500E-1	1.020E+0	9.500E-1	9.928E-1	9.000E-1	9.434E-1	9.500E-1	8.469E-1
9.750E-1	1.012E+0	9.750E-1	9.850E-1	9.500E-1	9.263E-1	9.600E-1	8.437E-1
9.800E-1	1.011E+0	9.800E-1	9.835E-1	9.750E-1	9.181E-1	9.700E-1	8.405E-1
9.850E-1	1.011E+0	9.850E-1	9.835E-1	9.800E-1	9.165E-1	9.800E-1	8.373E-1
				9.850E-1	9.165E-1	9.850E-1	8.373E-1

Table A4. Spline data for the calculated variational parameter ξ_v/ξ_{v0} at $5 \leq k < 50$.

$k = 5$		$k = 10$		$k = 20$		$k = 50^*$	
\bar{b}	ξ_v/ξ_{v0}	\bar{b}	ξ_v/ξ_{v0}	\bar{b}	ξ_v/ξ_{v0}	\bar{b}	ξ_v/ξ_{v0}
2.000E-7	1.001E+0	4.000E-6	1.000E+0	1.000E-8	1.001E+0	7.025E-9	9.989E-1
1.000E-6	1.001E+0	9.090E-6	1.000E+0	1.000E-6	1.001E+0	9.000E-6	1.001E+0
9.090E-6	1.001E+0	3.287E-5	1.000E+0	9.090E-6	1.001E+0	1.500E-5	1.001E+0
3.287E-5	1.001E+0	1.073E-4	1.004E+0	3.287E-5	1.002E+0	3.287E-5	1.002E+0
1.073E-4	1.004E+0	3.456E-4	1.010E+0	1.073E-4	1.004E+0	1.073E-4	1.004E+0
3.456E-4	1.010E+0	1.121E-3	1.022E+0	3.456E-4	1.010E+0	3.456E-4	1.008E+0
1.121E-3	1.022E+0	3.682E-3	1.046E+0	1.121E-3	1.020E+0	1.121E-3	1.016E+0
3.682E-3	1.047E+0	1.000E-2	1.076E+0	3.682E-3	1.039E+0	3.682E-3	1.031E+0
1.000E-2	1.085E+0	2.500E-2	1.110E+0	1.000E-2	1.063E+0	1.000E-2	1.052E+0
2.500E-2	1.132E+0	5.000E-2	1.135E+0	2.500E-2	1.091E+0	2.500E-2	1.079E+0
5.000E-2	1.169E+0	7.000E-2	1.142E+0	5.000E-2	1.112E+0	5.000E-2	1.098E+0
7.000E-2	1.181E+0	1.000E-1	1.139E+0	7.000E-2	1.117E+0	7.000E-2	1.103E+0
1.000E-1	1.183E+0	1.500E-1	1.117E+0	1.000E-1	1.113E+0	1.000E-1	1.099E+0
1.500E-1	1.165E+0	2.000E-1	1.085E+0	1.500E-1	1.090E+0	1.500E-1	1.076E+0
2.000E-1	1.134E+0	2.250E-1	1.067E+0	2.000E-1	1.058E+0	2.000E-1	1.044E+0
2.250E-1	1.116E+0	2.500E-1	1.050E+0	2.250E-1	1.041E+0	2.250E-1	1.027E+0
2.500E-1	1.099E+0	3.000E-1	1.015E+0	2.500E-1	1.024E+0	2.500E-1	1.010E+0
3.000E-1	1.063E+0	3.500E-1	9.813E-1	3.000E-1	9.894E-1	3.000E-1	9.759E-1
3.500E-1	1.029E+0	4.000E-1	9.498E-1	3.500E-1	9.565E-1	3.500E-1	9.435E-1
4.000E-1	9.961E-1	4.500E-1	9.204E-1	4.000E-1	9.257E-1	4.000E-1	9.130E-1
4.500E-1	9.657E-1	5.000E-1	8.931E-1	4.500E-1	8.970E-1	4.500E-1	8.847E-1
5.000E-1	9.374E-1	5.500E-1	8.678E-1	5.000E-1	8.703E-1	5.000E-1	8.583E-1
5.500E-1	9.111E-1	6.000E-1	8.443E-1	5.500E-1	8.456E-1	5.500E-1	8.339E-1
6.000E-1	8.866E-1	6.500E-1	8.224E-1	6.000E-1	8.226E-1	6.000E-1	8.113E-1
6.500E-1	8.639E-1	7.000E-1	8.020E-1	6.500E-1	8.013E-1	6.500E-1	7.902E-1
7.000E-1	8.426E-1	7.500E-1	7.830E-1	7.000E-1	7.814E-1	7.000E-1	7.706E-1
7.500E-1	8.227E-1	8.000E-1	7.652E-1	7.500E-1	7.628E-1	7.500E-1	7.523E-1
8.000E-1	8.041E-1	8.500E-1	7.485E-1	8.000E-1	7.455E-1	8.000E-1	7.352E-1
8.500E-1	7.867E-1	9.000E-1	7.328E-1	8.500E-1	7.292E-1	8.500E-1	7.191E-1
9.000E-1	7.702E-1	9.500E-1	7.180E-1	9.000E-1	7.139E-1	9.000E-1	7.040E-1
9.500E-1	7.548E-1	9.750E-1	7.110E-1	9.500E-1	6.995E-1	9.500E-1	6.898E-1
9.700E-1	7.488E-1	9.800E-1	7.096E-1	9.750E-1	6.926E-1	9.750E-1	6.829E-1
9.800E-1	7.459E-1	9.825E-1	7.089E-1	9.800E-1	6.912E-1	9.800E-1	6.817E-1
9.850E-1	7.459E-1	9.830E-1	7.088E-1	9.830E-1	6.904E-1	9.850E-1	6.817E-1
		9.850E-1	7.088E-1	9.850E-1	6.904E-1		

*same values as in **Table A2** are given here for convenience.

Table A5. The dimensional and dimensionless quantities and scaling factors.

Dimensional quantity	Dimensionless quantity	Remark
λ	$\lambda/\xi k = 1$	
ξ	$\frac{\xi}{\xi k} = \frac{1}{k}$	
r	$\frac{r}{\xi k}$	
πR^2	$\Phi_0/\bar{b}_k = 2\pi/k\bar{b}_k$	
$ \psi $	$\frac{ \psi }{\sqrt{\alpha/\beta}}$	
$f(r)$	$\frac{f(r)}{f_\infty}$	
g	g	2π
$a_\varphi(r)$	$\frac{a_\varphi(r)}{k\xi B_c\sqrt{2}} = \frac{a_\varphi(r)}{\xi B_{c2}}$	$\xi B_{c2} = \frac{\Phi_0}{2\pi\xi}$
B	$\frac{H}{kH_c\sqrt{2}} = \frac{H}{H_{c2}}$	$B = \mu_0 H$
B_{c1}	$\frac{H_{c1}}{H_c\sqrt{2}}$	$B_c = \frac{k_{12} B_{c2}}{k}$
B_{c2}	$\frac{B_{c2}}{B_c\sqrt{2}} = k$	$B_{c2} = \mu_0 H_{c2}$
B_c	$\frac{B_c}{B_c\sqrt{2}} = \frac{1}{\sqrt{2}}$	$k_{12} = \frac{1}{\sqrt{2}}$
$j_\varphi(r)$	$\frac{j_\varphi(r)\xi k}{H_c\sqrt{2}}$	
$q_\varphi(r)$	$\frac{q_\varphi(r)}{k\xi B_c\sqrt{2}} = \frac{q_\varphi(r)}{\xi B_{c2}}$	$\frac{B_{c2}}{B_c\sqrt{2}} = k$
Φ_0	$\frac{\Phi_0}{\lambda^2 \mu_0 H_c\sqrt{2}} = \frac{2\pi}{\mu_0 k}$	$B_{c2} = \frac{\Phi_0}{2\pi\xi^2}$
F	$\frac{F}{\mu_0 H_c^2}$	$\frac{F}{k^2 \mu_0 H_c^2} = \frac{2F}{\mu_0 H_{c2}^2}$
M_0	$\frac{M_0}{B_c\sqrt{2}}$ and $\frac{M_0}{B_{c2}}$	

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